combinatorial optimization for water management

Sophia-Antipolis, 13 november 2023





water management?

a commodity to collect, treat, distribute, value

ex: design and operate wastewater networks under normal or extreme conditions

a resource with limited availability to mobilize in processes

ex: withdraw water for cooling or cleaning while preserving water source quality

a biotope to preserve or a natural hazard to deal with

ex: adapt landscape to flood resilience

decision & management

accuracy



Operational effective process





Tactical system design





Strategic long-term planning



time

during the next hour

overview of prescriptive tools in decision support

focus on mathematical optimization and discrete decision

selected applications in water management



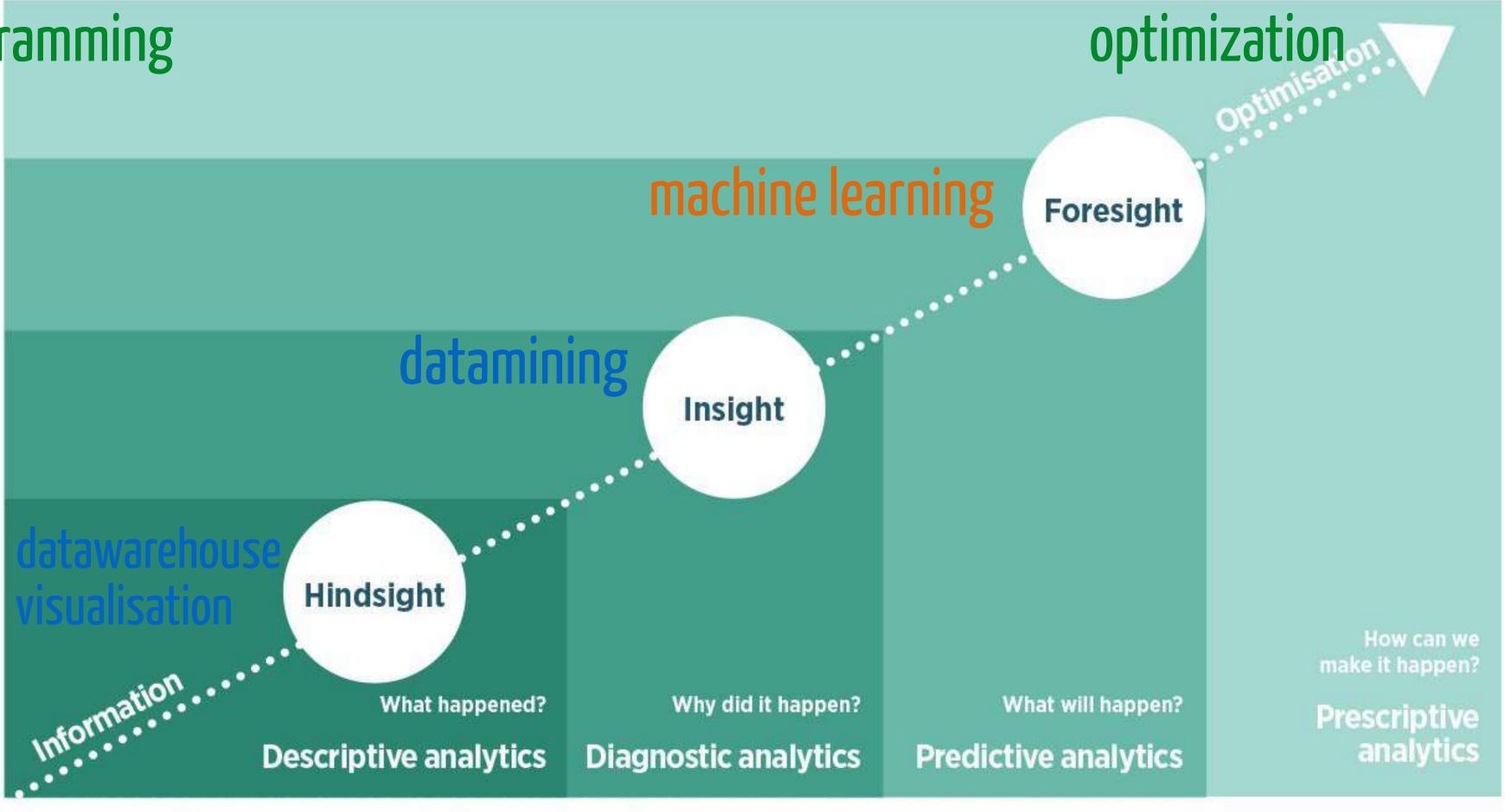
decision support

from WWII:

mathematical programming

in the 2010s: Al, deep learning

in the 2000s: business analytics, big data



Difficutly

decision = optimization

Decision Making

identify possible alternatives, attach a quantitative score, search an alternative with the highest score

Optimization

model: describe the feasible solutions

objective: a mapping from solutions to scores

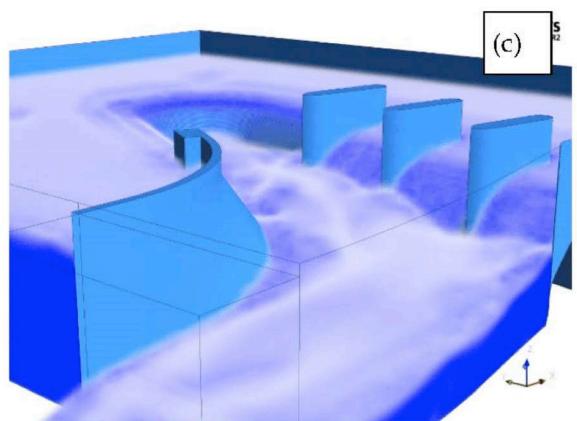
optimize: compute a feasible solution of maximum score

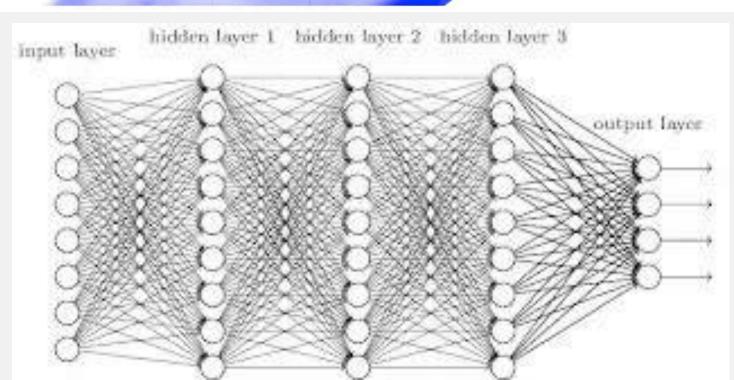
physical and virtual/numerical models

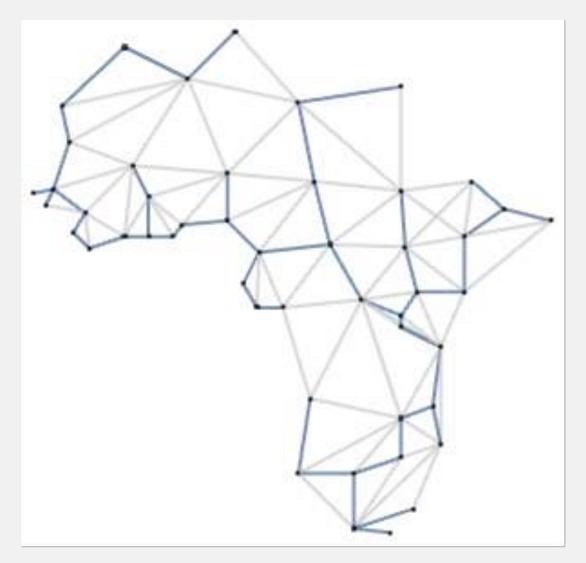
simulators: imperative "how"

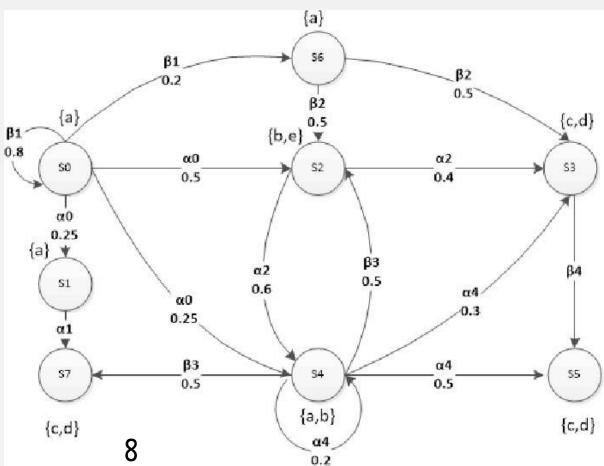












models

$$\min \sum_{k=1}^{K} \sum_{j=1}^{n} d_{jk}$$

$$s.t. d_{jk} \ge \sum_{i=1}^{p} (m_{j}^{i} - y_{k}^{i})^{2} - \overline{d}_{jk}(1 - x_{jk}) \quad \forall j, k$$

$$\sum_{k=1}^{K} x_{jk} = 1 \quad \forall j$$

$$x_{jk} \in \{0,1\}, y_{k}^{i} \in \mathbb{R}, d_{jk} \ge 0$$

$$\begin{array}{c|c} \Delta; \Gamma, \alpha & \Delta; \Gamma, \beta \\ \hline \Delta; \Gamma, \alpha_1 + \Delta; \Gamma, \alpha_2 & \overline{\Delta}; \Gamma, \overline{\Gamma} + \Delta; \Gamma, \beta_1, \beta_2 & \overline{\beta} \\ \hline \Delta; \Gamma, \neg \neg A \\ \Delta; \Gamma, A & \overline{\Delta}; \Gamma, A & \overline{\Delta}; \Gamma, \overline{\Gamma} \\ \hline \Delta, \alpha_1, \alpha_2; \Gamma & \overline{\Delta}, \overline{\Lambda}; \Gamma \\ \hline \Delta, A, \neg A; \Gamma \\ \hline \Delta, B; \Gamma & \overline{\Delta}, \overline{\Lambda}; \Gamma \\ \hline \Delta, \overline{\Lambda}; \Gamma & \overline{\Delta}; \Gamma, \overline{\Lambda} & \overline{\Delta}; \Gamma, \overline{\Lambda} \\ \hline \Delta, A, \overline{\Lambda}; \Gamma & \overline{\Delta}; \Gamma \\ \hline \Delta, A, \overline{\Lambda}; \Gamma & \overline{\Delta}; \Gamma \\ \hline \Delta, \overline{\Lambda}; \Gamma & \overline{\Delta}; \Gamma, \overline{\Lambda} & \overline{\Delta}; \Gamma, \overline{\Lambda} \\ \hline \Delta, A, \overline{\Lambda}; \Gamma & \overline{\Lambda}; \Gamma & \overline{\Lambda}; \Gamma \\ \hline \Delta, \overline{\Lambda}; \Gamma, \overline{\Lambda} & \overline{\Lambda}; \Gamma, \overline{\Lambda} \\ \hline \end{array}$$

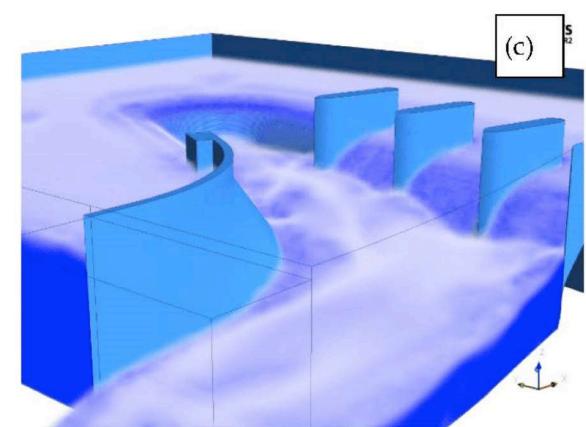
conceptual models

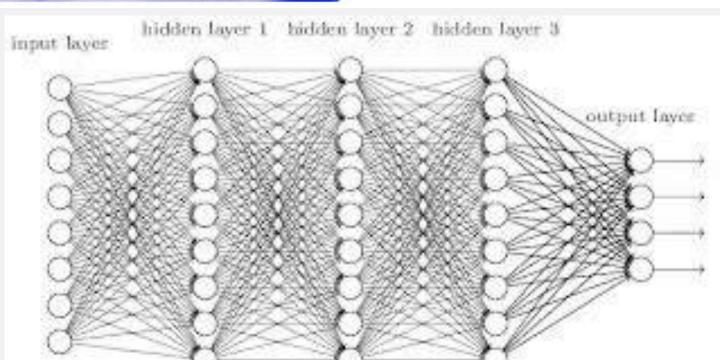
formulation: declarative "what"

models

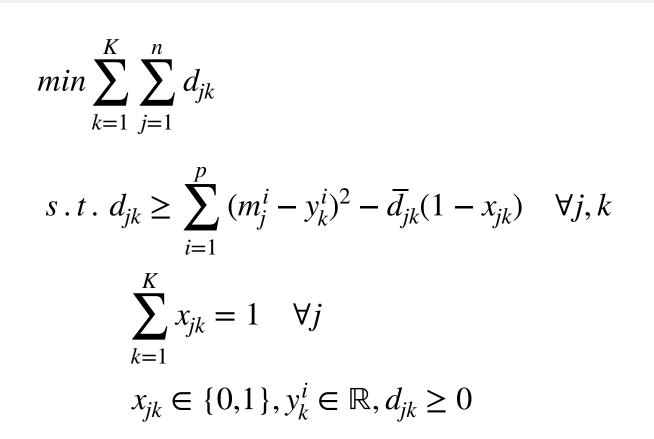


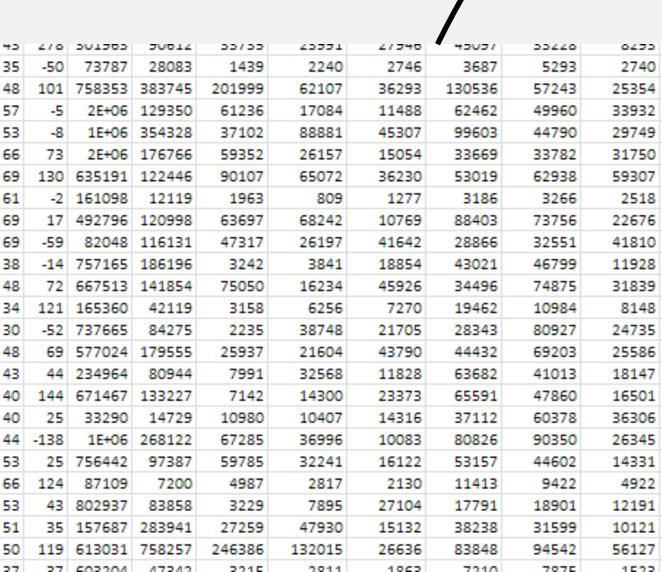






built by experts
or automatically from data
(machine learning)





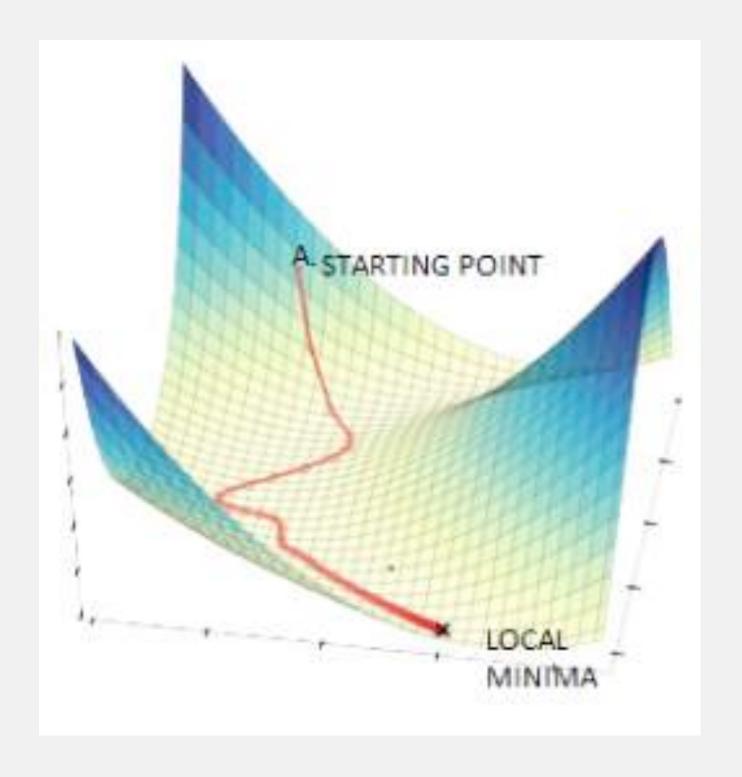
optimize (black-box)

numerical methods:

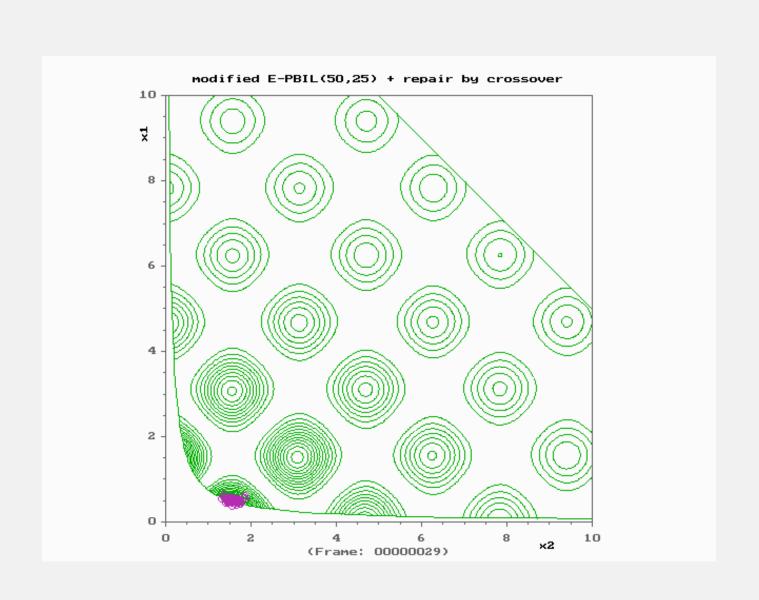
- 1. select a candidate decision
- 2. simulate/evaluate feasibility and score
- 3. stop or iterate

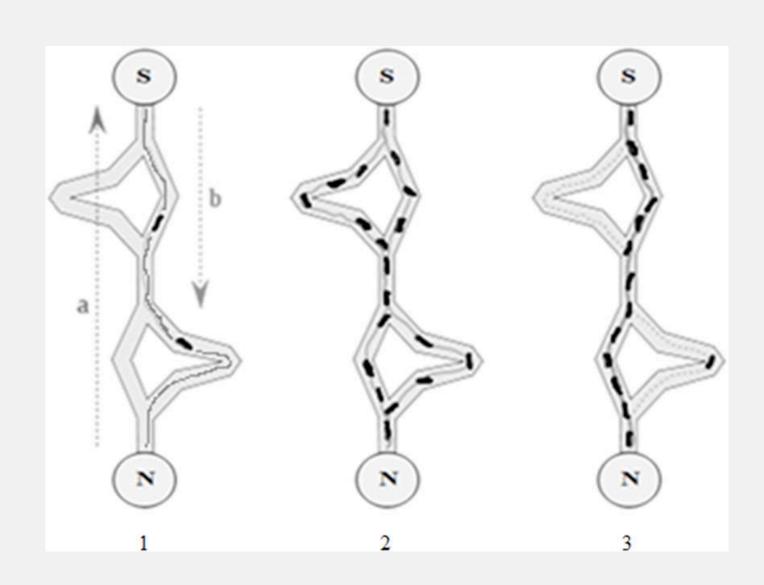
search: which candidates to evaluate?

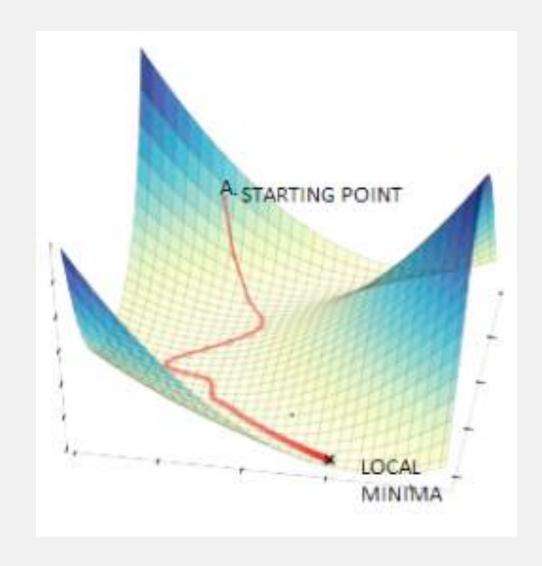
- partial, exhaustive, exhaustive but implicit
- random or directed by the proximity, the scores or highest-order information



optimize (black-box)







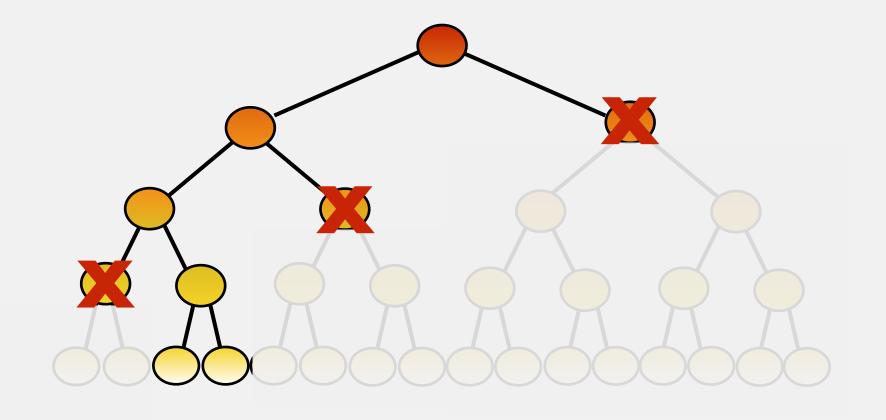
examples:

- local search: move to a neighbour candidate, the best one or in an improving direction (may converge to a global optimum, e.g. gradient descent in convex optimization, simplex algorithm in linear programming)
- metaheuristics (evolutionary, swarm): combine candidates, use collective memory

optimize (relaxation)

divide-and-conquer:

- 1. separate the search space (and refine the model)
- 2. estimate feasibility and best score in a simpler relaxed model
- 3. backtrack if not better, record if full solution, or iterate



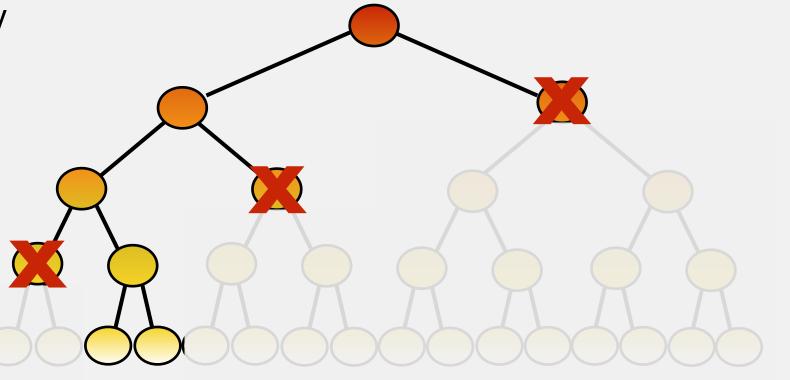
bounding the maximal score:

- certificate of optimality: gap between relaxations (UB) and full solutions (LB)
- rely on tight but simple relaxations

optimize (relaxation)

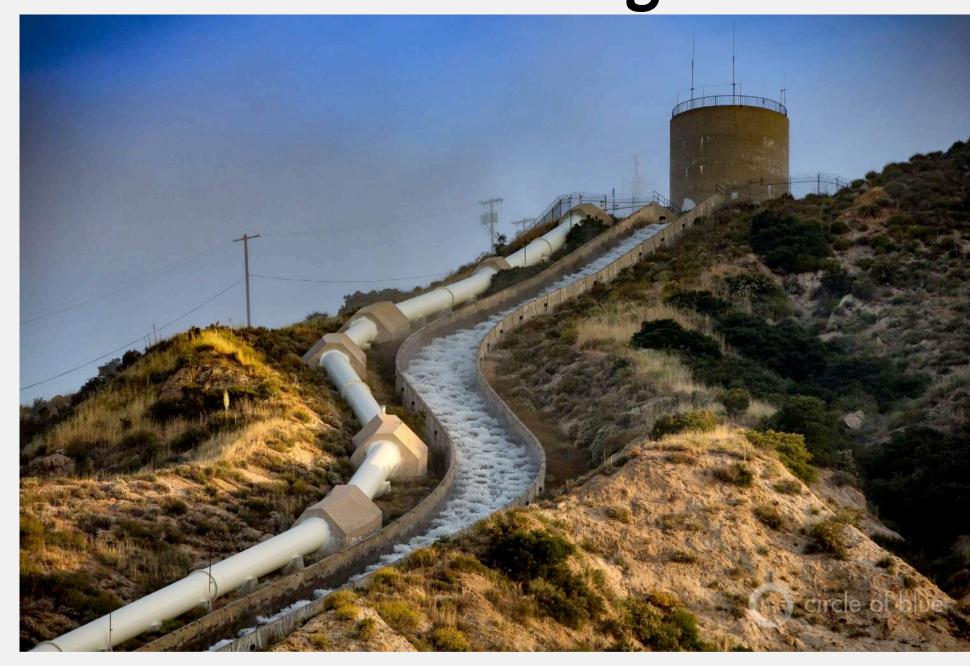
examples:

- greedy algorithm: no backtrack, no certificate of optimality
- graph algorithms, dynamic programming
- backtracking methods in logic/constraint programming
- branch-and-bound in combinatorial optimization



accuracy & approximation

Decision Making



Mathematical Optimization

$$\min_{x \in \mathbb{R}^n} f(x) : g_i(x) = 0 \ \forall i = 1, ..., m$$

concrete problem

practical decision

abstract model

optimal solution





solve a model not a problem

- imprecise (truncated) and uncertain (forecast) data
- approximate dynamics and simplified (soften) constraints
- conceptual objective

solve?

- solution may be infeasible or feasible with a tolerance gap
- solution may be sub-optimal or optimal with a tolerance gap
- solution may not be provably optimal, neither globally nor locally
- theoretic complexity and convergence give no practical guarantees



mathematical optimization

mathematical program

$$\min f(x): g(x) \le 0, \ x \in \mathbb{Z}^p \times \mathbb{R}^{n-p}$$

 $f: \mathbb{R}^n \mapsto \mathbb{R} \text{ objective}$ $g: \mathbb{R}^n \times \mathbb{R}^m \mapsto \mathbb{R}^m \text{ constraints}$

 $x \in \mathbb{R}^n$ variables / solution

mathematical program

$$\min f(x) : g(x) \le 0, x \in \mathbb{Z}^p \times \mathbb{R}^{n-p}$$

well-solved classes:

f,g linear p=0 linear programming f convex, $g\equiv 0$, p=0 unconstrained optimization f,g smooth convex p=0 convex programming f,g linear p>1 mixed integer linear programming

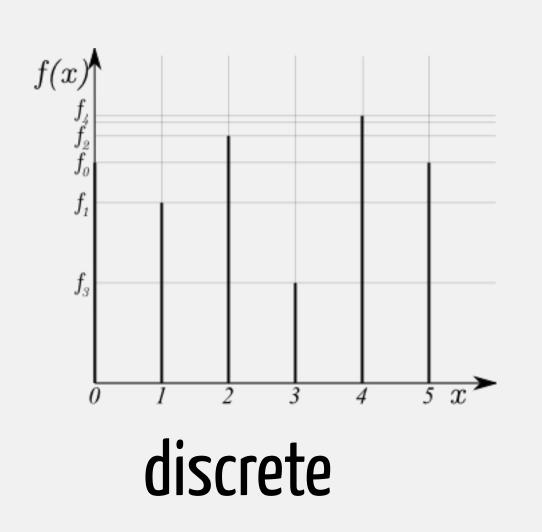
Mixed Integer Linear Program

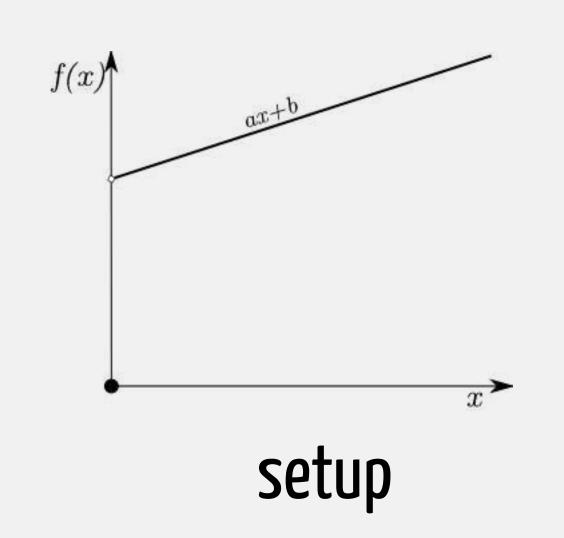
covers discrete decisions: off/on status $x \in \{0,1\}$, operation level $l \in \{0,1,\ldots,N\}$

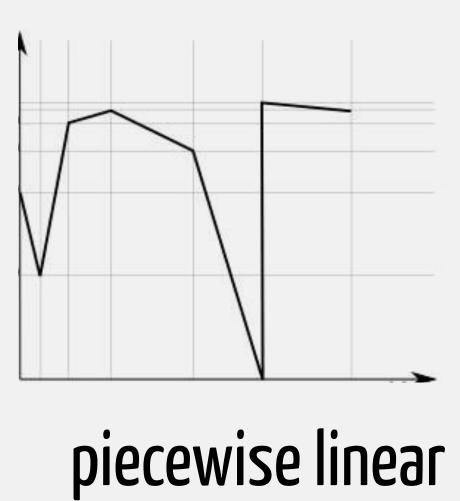
covers logical relations: $l \le N(1-x)$ level is 0 if status is on: $x=1 \implies l=0$

covers nonlinear relations: $l = \sum_{i=0}^{N} ix_i, y = \sum_{i=0}^{N} f_i x_i, 1 = \sum_{i=0}^{N} x_i, x_i \in \{0,1\} \, \forall i \in \{0,...,N\}$

y = f(l) a discrete function



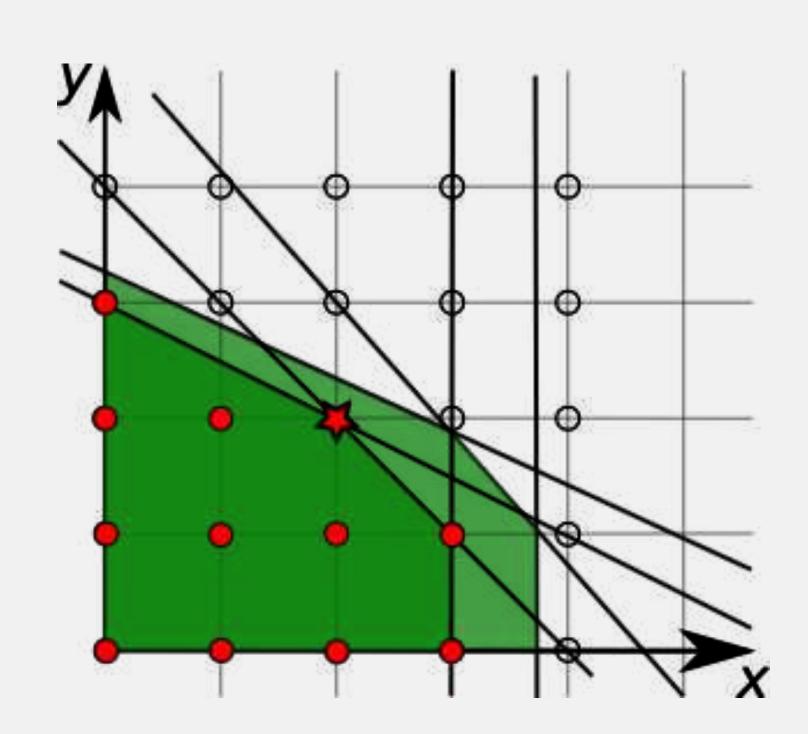


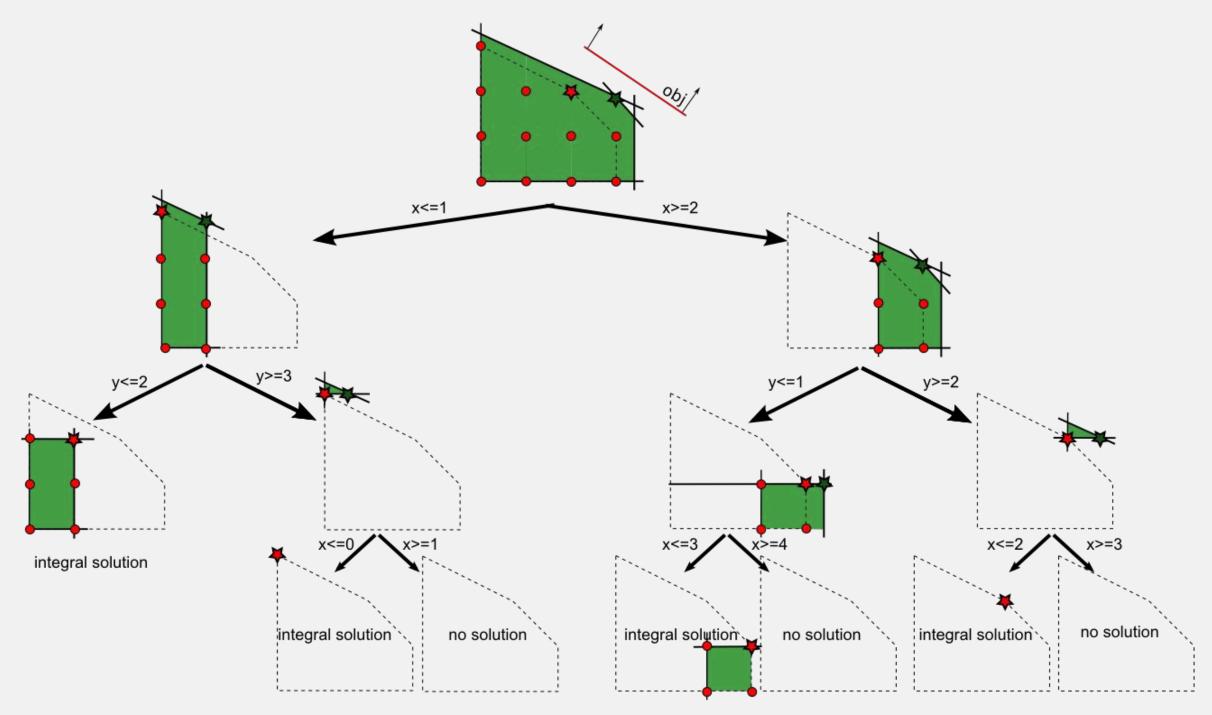


MILP algorithms

cutting-plane algorithm branch-and-bound branch-and-cut

- based on the LP relaxation
- evaluate, refine, iterate
- separate (on discrete variables), estimate, backtrack/iterate
- refine then estimate





declarative equations, not algorithms

performance sophisticated solvers

versatile covers logic & nonlinear

optimality primal-dual bounds

MILP perks

large-scale decomposition methods

flexible general-purpose format & solvers

declarative

performance *good model? sophisticated solvers

*still NP-hard: scale to some extent (or consider LP)

optimality primal-dual bounds

MILP perks*

versatile
covers logic & nonlinear
*approximation
(or consider MINLP)

decomposition methods
*algorithmic challenge

flexible
general-purpose format & solvers
*generic \neq best



water optimization

Wateris

a commodity, a resource, an environment

drinking water

wastewater

rain, ice, surface water, ground water

fresh, brackish, saline water

irrigation water

source of hydropower (river, tide, wave)

vector of pumped-storage hydroelectricity

steam to generate heat and energy

water for cooling or cleaning

water for processing (fracking, diluting, drilling)

storms, floods, droughts, mudflows, tsunamis

subject to thermal, chemical pollution

related to climate change, climate variability

wetlands, rain forests, oceans, coasts and rivers

to process

extract,

supply,

treat,

produce,

irrigate,

desalinate,

purify,

drain,

heat,

blend,

store,

pump,

flow,

preserve,

measure,

prevent,

control

in small/large systems

urban networks

sewers

desalination plants

farms

power systems

hydropower plants

thermal plants

industries

municipalities

pumps, turbines

aquifers

drainage basins

ecosystems

world

water optimization



organize the process

select elements to operate assign operation level allocate resources schedule operations position elements



design the system

select elements to dimension, maintain assign dimension, equipment plan resources and times

often discrete decisions nonlinear physical dynamics minimize an economic/social/ecological cost

study cases

urban water networks

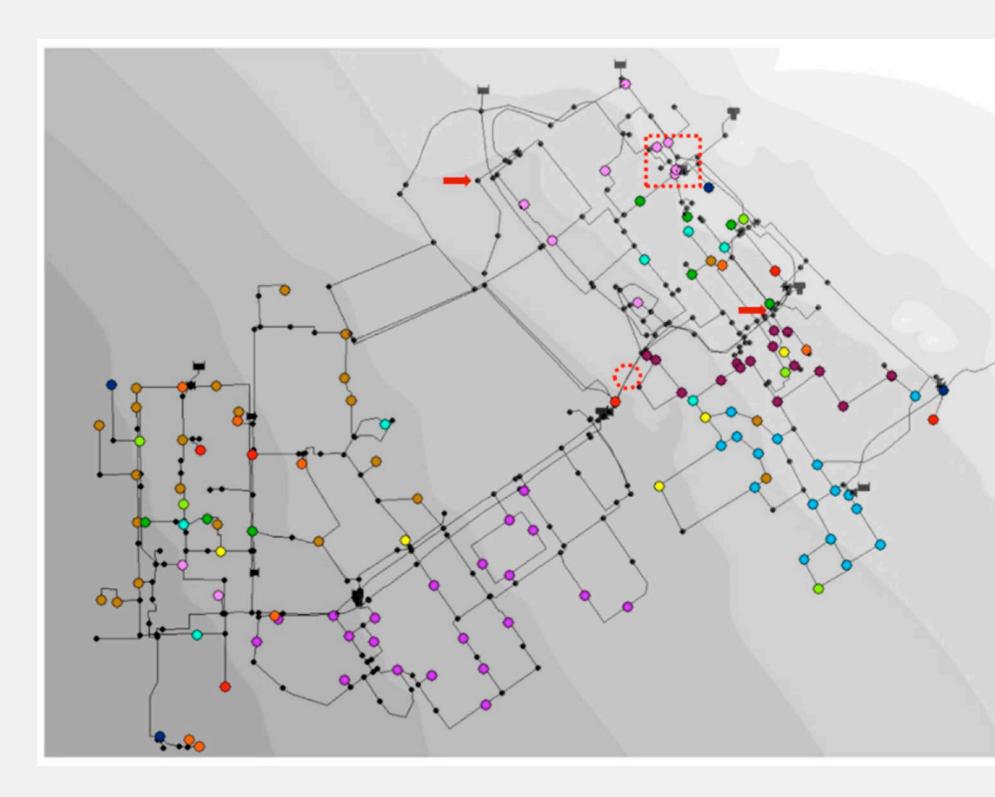
groundwater abstraction

hydroelectricity production



ex1: pipe sizing

select the size of the pipes in a gravity-fed network to satisfy the demand at each delivery node while minimizing the installation costs



finite catalog of pipes:





ex1: pipe sizing

assign a size k to each pipe a: $x_{ak} = 1$ (otherwise $x_{ak} = 0$)

hydraulic equilibrium between flows q and heads h, v in the selected network

$$\min_{x,q,h} \sum_{a} \sum_{k} c_{ak} x_{ak}$$

$$s.t. x_{ak} = 0 \implies q_{ak} = v_{ak} = 0$$

$$\sum_{k} x_{ak} = 1, h_i - h_j = \sum_{k} v_{ak}$$

$$(q_{AK}, h_S) \in NAP(D_S, H_R, \phi_{AK(x)}).$$

$$\forall a \in A, k \in K$$

$$\forall a = (i, j) \in A$$

bilevel program or simulation-based genetic algorithm

convex MINLP or approximate MILP + branch-and-bound

ex1: pipe sizing

convex MINLP reformulation

$$\min_{x,q,h} \sum_{a} \sum_{k} c_{ak} x_{ak}$$

$$s.t. x_{ak} = 0 \implies q_{ak} = v_{ak} = 0$$

$$\sum_{k} x_{ak} = 1, h_i - h_j = \sum_{k} v_{ak}$$

$$\sum_{k} E_{as} q_{ak} = D_s$$

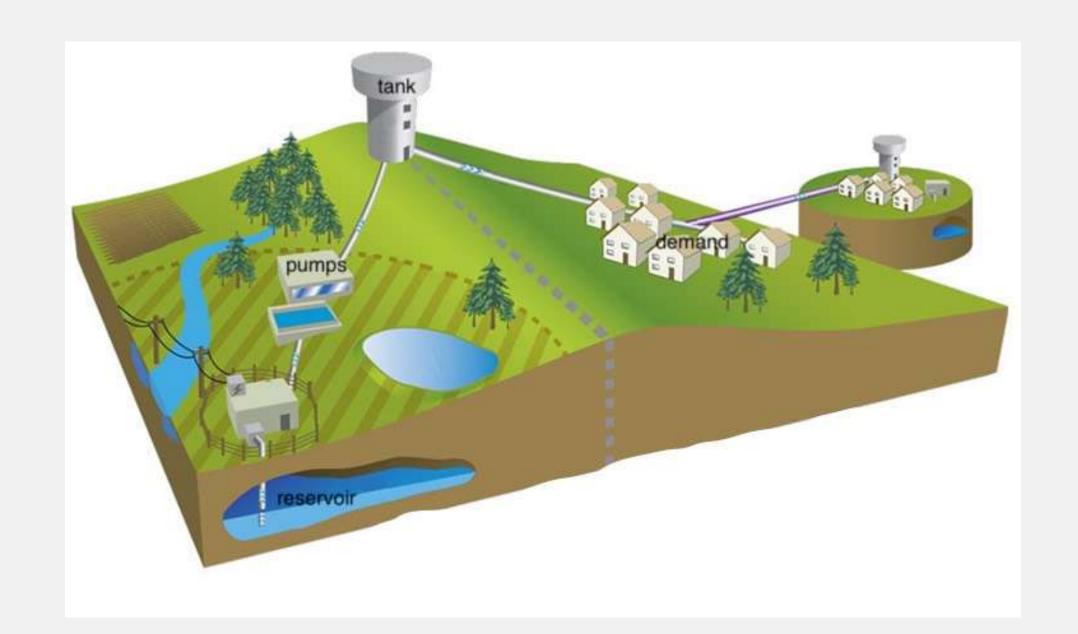
$$\sum_{ak} \left(f_{ak} (q_{ak}) + f_{ak}^* (v_{ak}) \right) + H_R^\top q_R + D_S^\top h_S \le 0$$

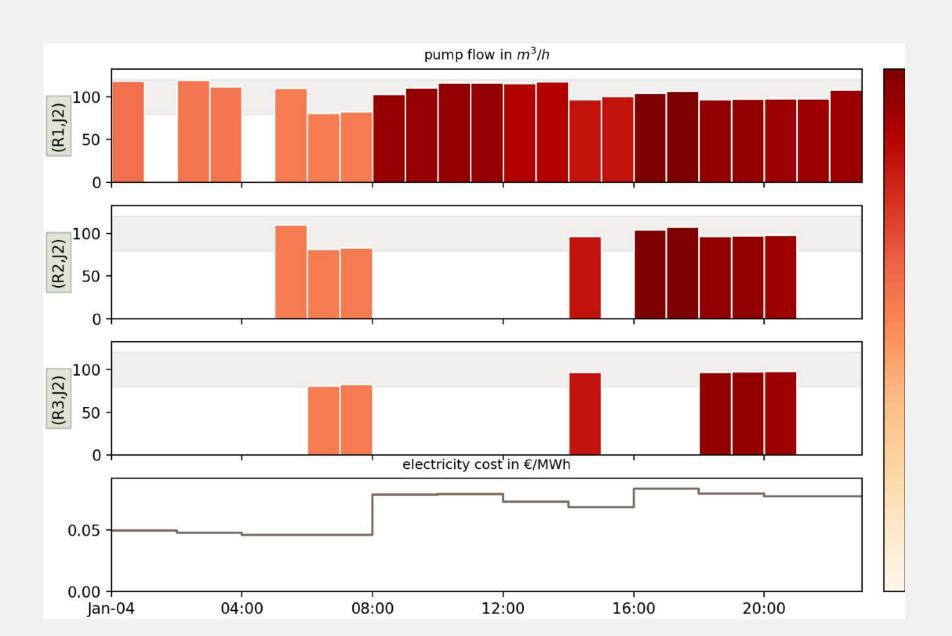
$$(SD)$$

[Demassey. Strong duality reformulation for bilevel optimization over nonlinear flow networks. 2023]

ex2: pump scheduling (load shifting in pressurized networks)

schedule pumps and valves in a pressurized network on a time horizon to satisfy the varying demand at each delivery node and the capacity of the water tanks while minimizing the electricity bill





ex2: pump scheduling

activate pump/valve a at time t: $x_{at} = 1$ (otherwise $x_{at} = 0$)

hydraulic equilibrium between flows q and heads h, v in the active network

limit the water tank level $oldsymbol{H}$

$$\min \sum_{a} \sum_{t} c_{at}^{0} x_{at} + c_{at}^{1} q_{at}$$

$$s.t.(q_{At}, h_{St}) \in NAP(D_{St}, H_{Rt}, \phi_{A(x_{t})}) \qquad \forall t \in T$$

$$x_{at} = 0 \implies q_{at} = 0 \qquad \forall a \in A, t \in T$$

$$H_{R(t+1)} = H_{Rt} + s_{R}^{\top} q_{Rt} \qquad \forall t \in T$$

$$\underline{H}_{Rt} \leq H_{Rt} \leq \overline{H}_{Rt} \qquad \forall t \in T.$$

additional complexity: temporal inter-dependency

[Demassey Strong duality reformulation for bilevel optimization over nonlinea²flow networks. 2023]

water network optimization (drinking, waste, irrigation)

decisions

dimension renovation extension sectorization scheduling operations scheduling maintenance place equipments and controllers calibrate hydraulic models concerns

demand: standard, worst-case, emergy network topology energy consumption leakage, over-pressure flow conservation pressure-flow relation chlorine consumption water quality, treatment storage capacity resilience to failures or storms sewer overflow

[Bello, et al. Solving Management Problems in Water Distribution Networks: A Survey of Approaches and Mathematical Models. Water 2019]
[Mala-Jetmarova, Sultanova, Savic. Lost in Optimisation of Water Distribution Systems? A Literature Review of System Design. Water 2018]



ex3: sustainable abstraction

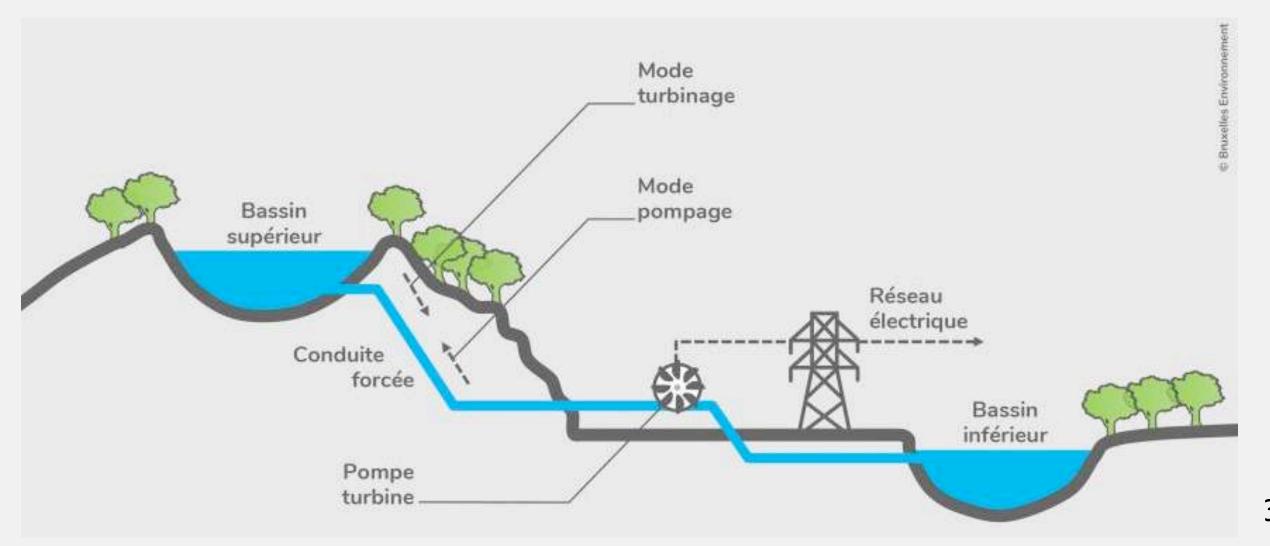
place pumps and plan pumping to prevent aquifer depletion (then land subsidence or seawater intrusion) and quality degradation (temperature, salinity) while maximizing the abstraction value

strong uncertainties (aquifer recharge rate), approximate dynamics (quality) and sustainability models



ex4: hydro unit commitment

schedule pumps and turbine
to ensure flow conservation
and maintain reservoir level in their limits
w.r.t strategic constraints (load balance, ramp, irrigation)
while maximizing the power production value



(lagrangian) subproblem of day-to-day unit commitment encompassing national power systems

ex4: hydro unit commitment

flow q_{it} , volume v_{it} , power production/consumption p_{it} in plant i at time t nonlinear flow-power relation ϕ (turbine), disjunctive flow domains volume conservation and limits in reservoirs

$$\max \sum_{i \in I} \sum_{t \in T} \lambda_{it} p_{it}$$

$$p_{it} = \Phi(q_{it}, v_{it}) \quad \forall t, \forall i \quad (2)$$

$$v_{it} = v_{i(t-1)} + I_{it} + \Delta T(-q_{it} + \sum_{r \in I_i^+} q_{r(t-1)} - \sum_{r \in I_i^-} q_{r(t-1)}) \quad \forall t, \forall i \quad (3)$$

$$q_{it} \in \{Q_i^-\} \cup \{0\} \cup [\underline{Q}_i, \overline{Q}_i] \quad \forall t, \forall i \quad (4)$$

$$\underline{V}_i \leq v_{it} \leq \overline{V}_i \quad \forall t, \forall i \quad (5)$$

[Taktak & d'Ambrosio. <u>An overview on mathematical programming approaches for the deterministic unit commitment problem in hydro valleys</u>. Energy Sys 2017]

CONCIUSION

- huge diversity of water systems & processes
- management involves decision involves optimization, e.g. maximize sustainability
- mathematical optimization as a low-tech solution (except computation and data acquisition) to get as much out of existing investments
- uncertain forecasts, intricated systems, nonlinear dynamics, fuzzy objectives: trade-off between accurate models and efficient algorithms

and next

- modelling sustainability accurately
- short/long-term model coupling: time-scale reconciliation to shed light on the plausibility of prospective pathways