5.98 cumulative_product			
	DESCRIPTION	LINKS	GRAPH
Origin	Derived from cumulative.		
Constraint	cumulative_product(TASKS,	LIMIT)	
Arguments	TASKS : collection $\begin{pmatrix} o \\ d \\ e \\ h \end{pmatrix}$ LIMIT : int	rigin-dvar, uration-dvar, nd-dvar, eight-dvar	
Restrictions	$\begin{array}{l} \textbf{require\_at\_least}(2, \texttt{TASKS} \\ \textbf{required}(\texttt{TASKS}, \texttt{height}) \\ \texttt{TASKS.duration} \geq 0 \\ \texttt{TASKS.origin} \leq \texttt{TASKS.end} \\ \texttt{TASKS.height} \geq 1 \\ \texttt{LIMIT} \geq 0 \end{array}$	,[origin,duration,	end])
Purpose	constraint forces that at each po that overlap that point, does no	int in time, the product texceed a given limit or equal to $i$ , and (2)	ction. The cumulative_product ct of the heights of the set of tasks i. A task overlaps a point $i$ if and its end is strictly greater than $i$ . It n + duration = end.
Example	$\left(\begin{array}{c} \text{origin}-1 & \text{durat} \\ \text{origin}-2 & \text{durat} \\ \text{origin}-3 & \text{durat} \\ \text{origin}-6 & \text{durat} \\ \text{origin}-7 & \text{durat} \end{array}\right)$	ion - 3 end $- 4ion - 9$ end $- 11ion - 10$ end $- 13ion - 6$ end $- 12ion - 2$ end $- 9$	$ \begin{array}{c} \texttt{height} - 2, \\ \texttt{height} - 1, \\ \texttt{height} - 1, \end{array} \right\rangle, 6 \\ \end{array}$
	cumulative_product constrain colour: the sum of the lengths of while the height of the rectangle same height) corresponds to the	t corresponds a set of of the rectangles corre es (i.e., all the rectang e height of the task.	e example. To each task of the rectangles coloured with the same sponds to the duration of the task, les associated with a task have the The profile corresponding to the on point is depicted by a thick and

product of the heights of the tasks that overlap a given point is depicted by a thick red line. The cumulative\_product constraint holds since at each point in time the product of the heights of the tasks that overlap that point is not strictly greater than the upper limit

 $6 \ {\rm enforced} \ {\rm by} \ {\rm the} \ {\rm last} \ {\rm argument} \ {\rm of} \ {\rm the} \ {\rm cumulative\_product} \ {\rm constraint}.$ 

## = 00 . .... ъ

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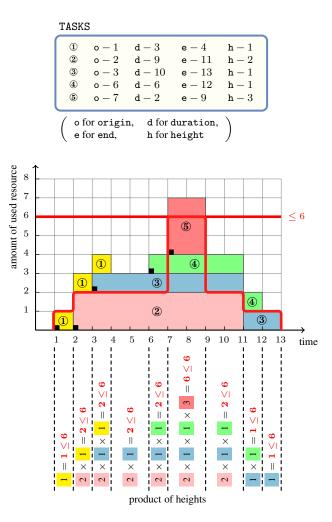


Figure 5.220: Resource consumption profile in red corresponding to the product of the heights of the five tasks of the **Example** slot

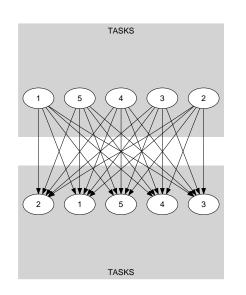
Typical

$$\begin{split} |\texttt{TASKS}| > 1 \\ \texttt{range}(\texttt{TASKS.origin}) > 1 \\ \texttt{range}(\texttt{TASKS.origin}) > 1 \\ \texttt{range}(\texttt{TASKS.duration}) > 1 \\ \texttt{range}(\texttt{TASKS.end}) > 1 \\ \texttt{range}(\texttt{TASKS.height}) > 1 \\ \texttt{TASKS.duration} > 0 \\ \texttt{LIMIT} < \texttt{prod}(\texttt{TASKS.height}) \end{split}$$

Symmetries	• Items of TASKS are permutable.		
	• TASKS.height can be decreased to any value $\geq 0$ .		
	• One and the same constant can be added to the origin and end attributes of all items of TASKS.		
	• LIMIT can be increased.		
Arg. properties			
ing properties	Contractible wrt. TASKS.		
Reformulation	The cumulative_product constraint can be expressed in term of a set of reified constraints and of  TASKS  constraints of the form $h_1 \cdot h_2 \cdot \cdots \cdot h_{ TASKS } \leq l$ :		
	1. For each pair of tasks $TASKS[i]$ , $TASKS[j]$ $(i, j \in [1,  TASKS ])$ of the TASKS collection we create a variable $H_{ij}$ which is set to the height of task $TASKS[j]$ if task $TASKS[j]$ overlaps the origin attribute of task $TASKS[i]$ , and to 1 otherwise:		
	• If $i = j$ :		
	- $H_{ij} = \texttt{TASKS}[i].\texttt{height}.$		
	• If $i \neq j$ :		
	- $H_{ij} = \text{TASKS}[j]$ .height $\lor H_{ij} = 1$ .		
	$\begin{array}{l} - \ ((\texttt{TASKS}[j].\texttt{origin} \leq \texttt{TASKS}[i].\texttt{origin} \land \\ \\ \texttt{TASKS}[j].\texttt{end} > \texttt{TASKS}[i].\texttt{origin}) \land (H_{ij} = \texttt{TASKS}[j].\texttt{height})) \lor \end{array}$		
	$(( extsf{TASKS}[j]. extsf{origin} >  extsf{TASKS}[i]. extsf{origin} \lor \  extsf{TASKS}[j]. extsf{extsfract} =  extsf{TASKS}[i]. extsf{origin}) \land (H_{ij} = 1))$		
	2. For each task TASKS[i] $(i \in [1,  TASKS ])$ we impose a constraint of the form $H_{i1}$ .		
	2. For each task $[IASKS[i] \ (i \in [1, [IASKS]])$ we impose a constraint of the form $H_{i1}$ . $H_{i2} \cdots H_{i TASKS } \leq \text{LIMIT.}$		
See also	common keyword: cumulative (resource constraint).		
	used in graph description: product_ctr.		
Keywords	characteristic of a constraint: product.		
	constraint type: scheduling constraint, resource constraint, temporal constraint.		
	filtering: compulsory part.		
	modelling: zero-duration task.		

Arc input(s)	TASKS	
Arc generator	$SELF \mapsto \texttt{collection}(\texttt{tasks})$	
Arc arity	1	
Arc constraint(s)	tasks.origin + tasks.duration = tasks.end	
Graph property(ies)	NARC=  TASKS	
Arc input(s)	TASKS TASKS	
Arc generator	$PRODUCT \mapsto \texttt{collection}(\texttt{tasks1},\texttt{tasks2})$	
Arc arity	2	
Arc constraint(s)	<ul> <li>tasks1.duration &gt; 0</li> <li>tasks2.origin ≤ tasks1.origin</li> <li>tasks1.origin &lt; tasks2.end</li> </ul>	
Graph class	• ACYCLIC • BIPARTITE • NO_LOOP	
Sets	$ \begin{bmatrix} \text{SUCC} \mapsto \\ \text{source,} \\ \text{variables} - \text{col} \begin{pmatrix} \text{VARIABLES} - \text{collection}(\text{var} - \text{dvar}), \\ [\text{item}(\text{var} - \text{ITEMS.height})] \end{pmatrix} \end{bmatrix} $	
Constraint(s) on sets	$product\_ctr(variables, \leq, LIMIT)$	
Graph model	Parts (A) and (B) of Figure 5.221 respectively show the initial and final graph associated with the second graph constraint of the <b>Example</b> slot. On the one hand, each source vertex of the final graph can be interpreted as a time point. On the other hand the successors of a source vertex correspond to those tasks that overlap that time point. The cumulative_product constraint holds since for each successor set $S$ of the final graph the product of the tasks in $S$ does not exceed the limit LIMIT = 6.	

SignatureSince TASKS is the maximum number of vertices of the final graph of the first graph con-<br/>straint we can rewrite NARC = |TASKS| to  $NARC \ge |TASKS|$ . This leads to simplify<br/>NARC to NARC.



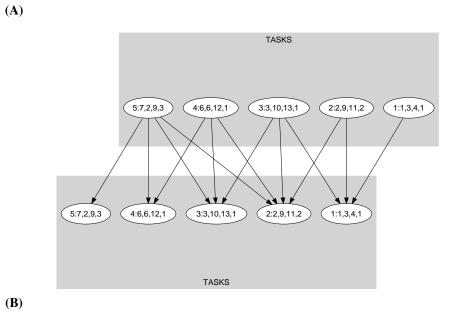


Figure 5.221: Initial and final graph of the cumulative\_product constraint