

5.134 dom_reachability

	DESCRIPTION	LINKS
Origin	[330]	
Constraint	$\text{dom_reachability} \left(\begin{array}{l} \text{SOURCE,} \\ \text{FLOW_GRAPH,} \\ \text{DOMINATOR_GRAPH,} \\ \text{TRANSITIVE_CLOSURE_GRAPH} \end{array} \right)$	
Arguments	<pre> SOURCE : int FLOW_GRAPH : collection(index-int, succ-svar) DOMINATOR_GRAPH : collection(index-int, succ-sint) TRANSITIVE_CLOSURE_GRAPH : collection(index-int, succ-svar) </pre>	
Restrictions	<pre> SOURCE ≥ 1 SOURCE ≤ FLOW_GRAPH required(FLOW_GRAPH, [index, succ]) FLOW_GRAPH.index ≥ 1 FLOW_GRAPH.index ≤ FLOW_GRAPH FLOW_GRAPH.succ ≥ 1 FLOW_GRAPH.succ ≤ FLOW_GRAPH distinct(FLOW_GRAPH, index) required(DOMINATOR_GRAPH, [index, succ]) DOMINATOR_GRAPH = FLOW_GRAPH DOMINATOR_GRAPH.index ≥ 1 DOMINATOR_GRAPH.index ≤ DOMINATOR_GRAPH DOMINATOR_GRAPH.succ ≥ 1 DOMINATOR_GRAPH.succ ≤ DOMINATOR_GRAPH distinct(DOMINATOR_GRAPH, index) required(TRANSITIVE_CLOSURE_GRAPH, [index, succ]) TRANSITIVE_CLOSURE_GRAPH = FLOW_GRAPH TRANSITIVE_CLOSURE_GRAPH.index ≥ 1 TRANSITIVE_CLOSURE_GRAPH.index ≤ TRANSITIVE_CLOSURE_GRAPH TRANSITIVE_CLOSURE_GRAPH.succ ≥ 1 TRANSITIVE_CLOSURE_GRAPH.succ ≤ TRANSITIVE_CLOSURE_GRAPH distinct(TRANSITIVE_CLOSURE_GRAPH, index) </pre>	

Let `FLOW_GRAPH`, `DOMINATOR_GRAPH` and `TRANSITIVE_CLOSURE_GRAPH` be three directed graphs respectively called the *flow graph*, the *dominance graph* and the *transitive closure graph* which all have the same vertices. In addition let `SOURCE` denote a vertex of the flow graph called the *source node* (not necessarily a vertex with no incoming arcs). The `dom_reachability` constraint holds if and only if the flow graph (and its source node) verifies:

Purpose

- The dominance relation expressed by the dominance graph (i.e., if there is an arc (i, j) in the dominance graph then, within the flow graph, all the paths from the source node to j contain i ; note that when there is no path from the source node to j then any node dominates j).
- The transitive relation expressed by the transitive closure graph (i.e., if there is an arc (i, j) in the transitive closure graph then there is also a path from i to j in the flow graph).

Example

$$\left(\begin{array}{l} 1, \left\langle \begin{array}{ll} \text{index} - 1 & \text{succ} - \{2\}, \\ \text{index} - 2 & \text{succ} - \{3, 4\}, \\ \text{index} - 3 & \text{succ} - \emptyset, \\ \text{index} - 4 & \text{succ} - \emptyset \end{array} \right\rangle, \\ \left\langle \begin{array}{ll} \text{index} - 1 & \text{succ} - \{2, 3, 4\}, \\ \text{index} - 2 & \text{succ} - \{3, 4\}, \\ \text{index} - 3 & \text{succ} - \emptyset, \\ \text{index} - 4 & \text{succ} - \emptyset \end{array} \right\rangle, \\ \left\langle \begin{array}{ll} \text{index} - 1 & \text{succ} - \{1, 2, 3, 4\}, \\ \text{index} - 2 & \text{succ} - \{2, 3, 4\}, \\ \text{index} - 3 & \text{succ} - \{3\}, \\ \text{index} - 4 & \text{succ} - \{4\} \end{array} \right\rangle \end{array} \right)$$

The flow graph, the dominance graph and the transitive closure graph corresponding to the second, third and fourth arguments of the `dom_reachability` constraint are respectively depicted by parts (A), (B) and (C) of Figure 5.290. The `dom_reachability` holds since the following conditions hold.

- The dominance relation expressed by the dominance graph is verified:
 - Since $(1, 2)$ belongs to the dominance graph all the paths from 1 to 2 in the flow graph pass through 1.
 - Since $(1, 3)$ belongs to the dominance graph all the paths from 1 to 3 in the flow graph pass through 1.
 - Since $(1, 4)$ belongs to the dominance graph all the paths from 1 to 4 in the flow graph pass through 1.
 - Since $(2, 3)$ belongs to the dominance graph all the paths from 1 to 3 in the flow graph pass through 2.
 - Since $(2, 4)$ belongs to the dominance graph all the paths from 1 to 4 in the flow graph pass through 2.
- The graph depicted by the fourth argument of the `dom_reachability` constraint (i.e., `TRANSITIVE_CLOSURE_GRAPH`) is the transitive closure of the graph depicted by the second argument (i.e., `FLOW_GRAPH`).

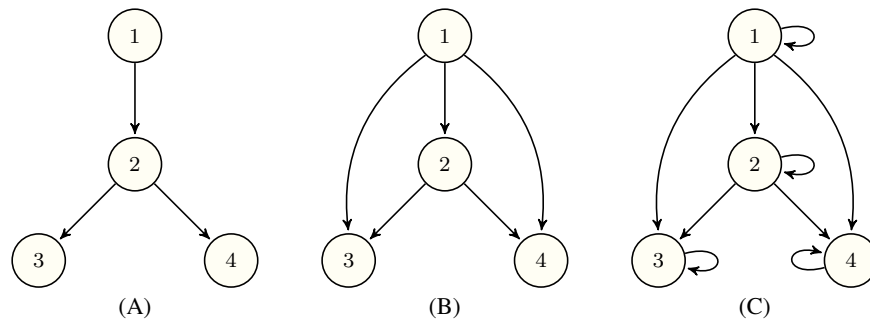


Figure 5.290: (A) Flow graph, (B) dominance graph and (C) transitive closure graph of the **Example** slot (taken from [328, page 40])

Typical	<code> FLOW_GRAPH > 2</code>
Symmetries	<ul style="list-style-type: none"> • Items of <code>FLOW_GRAPH</code> are permutable. • Items of <code>DOMINATOR_GRAPH</code> are permutable. • Items of <code>TRANSITIVE_CLOSURE_GRAPH</code> are permutable.
Usage	The <code>dom_reachability</code> constraint was introduced in order to solve reachability problems (e.g., disjoint paths, simple path with mandatory nodes).
Remark	Within the name <code>dom_reachability</code> , <code>dom</code> stands for <i>domination</i> . In the context of path problems <code>SOURCE</code> refers to the start of the path we want to build.
Algorithm	<p>It was shown in [328] that, finding out whether a <code>dom_reachability</code> constraint has a solution or not is NP-hard. This was achieved by reduction to <i>disjoint paths</i> problem [183].</p> <p>The first implementation [329] of the <code>dom_reachability</code> constraint was done in Mozart [121]. Later on, a second implementation [328] was done in Gecode [374]. Both implementations consist of the following two parts:</p> <ul style="list-style-type: none"> • Algorithms [362] for maintaining the lower bound of the transitive closure graph. • Algorithms for maintaining the upper bound of the transitive closure graph, while respecting the dominance constraints [192].
See also	common keyword: path , path_from_to (<i>path</i>).
Keywords	combinatorial object: path . constraint arguments: constraint involving set variables . constraint type: predefined constraint , graph constraint .

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