

5.404 tree_range

	DESCRIPTION	LINKS	GRAPH
Origin	Derived from tree .		
Constraint	<code>tree_range(NTREES, R, NODES)</code>		
Arguments	NTREES : <code>dvar</code> R : <code>dvar</code> NODES : <code>collection(index-int, succ-dvar)</code>		
Restrictions	$NTREES \geq 0$ $R \geq 0$ $R < NODES $ $ NODES > 0$ <code>required(NODES, [index, succ])</code> $NODES.index \geq 1$ $NODES.index \leq NODES $ <code>distinct(NODES, index)</code> $NODES.succ \geq 1$ $NODES.succ \leq NODES $		
Purpose	Cover the digraph G described by the NODES collection with NTREES trees in such a way that each vertex of G belongs to one distinct tree. R is the difference between the longest and the shortest paths (from a leaf to a root) of the final graph.		
Example	$2, 1, \left(\begin{array}{l} \text{index} - 1 \quad \text{succ} - 1, \\ \text{index} - 2 \quad \text{succ} - 5, \\ \text{index} - 3 \quad \text{succ} - 5, \\ \text{index} - 4 \quad \text{succ} - 7, \\ \text{index} - 5 \quad \text{succ} - 1, \\ \text{index} - 6 \quad \text{succ} - 1, \\ \text{index} - 7 \quad \text{succ} - 7, \\ \text{index} - 8 \quad \text{succ} - 5 \end{array} \right)$		
	The <code>tree_range</code> constraint holds since the graph associated with the items of the NODES collection corresponds to two trees (i.e., $NTREES = 2$): each tree respectively involves the vertices $\{1, 2, 3, 5, 6, 8\}$ and $\{4, 7\}$. Furthermore $R = 1$ is set to the difference between the longest path (for instance $2 \rightarrow 5 \rightarrow 1$) and the shortest path (for instance $4 \rightarrow 7$) from a leaf to a root. Figure 5.766 provides the two trees associated with the example.		
Typical	$NTREES < NODES $ $ NODES > 2$		
Symmetry	Items of NODES are permutable .		

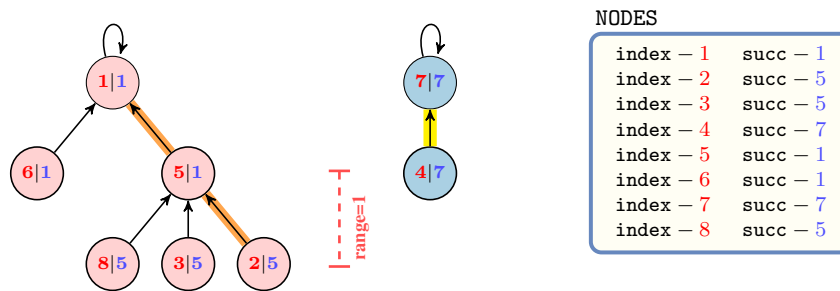


Figure 5.766: The two trees corresponding to the **Example** slot; each vertex contains the information `index|succ` where `succ` is the index of its father in the tree (by convention the father of the root is the root itself); the longest and shortest paths from a leaf to a root are respectively shown by thick orange and yellow line segments and have a length of 2 and 1; consequently the range is equal to 1.

Arg. properties

- **Functional dependency:** NTREES determined by NODES.
- **Functional dependency:** R determined by NODES.

Reformulation

By introducing a *distance variable* D_i , an *occurrence variable* O_i and a *leave variable* L_i ($1 \leq i \leq |\text{NODES}|$) for each item i of the NODES collection, where:

- D_i represents the number of vertices from i to the root of the corresponding tree,
- O_i gives the number of occurrences of value i within variables $\text{NODES}[1].\text{succ}, \text{NODES}[2].\text{succ}, \dots, \text{NODES}[n].\text{succ}$,
- L_i is set to 1 if item i corresponds to a leaf (i.e., $O_i > 0$) and 0 otherwise,

the `tree_range(NTREES, R, NODES)` constraint can be expressed in term of a conjunction of one `tree` constraint, $|\text{NODES}|$ `element` constraints, $|\text{NODES}|$ linear constraints, one `global_cardinality` constraint, $|\text{NODES}|$ reified constraints, one `open_minimum`, one `maximum` and one linear constraint, where:

- The `tree` constraint models the fact that we have a forest of NTREES trees.
- Each `element` constraint provides the link between the attribute `succ` of the i -th item and the distance variable $D_{\text{NODES}[i].\text{succ}}$ associated with item $\text{NODES}[i].\text{succ}$.
- Each linear constraint associated with the i -th item states that the difference between the distance variable D_i and the distance variable $D_{\text{NODES}[i].\text{succ}}$ is equal to 1.
- The `global_cardinality` constraint provides the number of occurrences O_i of value i ($1 \leq i \leq |\text{NODES}|$) within variables $\text{NODES}[1].\text{succ}, \text{NODES}[2].\text{succ}, \dots, \text{NODES}[|\text{NODES}|].\text{succ}$. Note that, when O_i is equal to 0, the corresponding i -th item is a leaf of one of the NTREES trees.
- Each reified constraint of the form $L_i \Leftrightarrow O_i > 0$ makes the link between the i -th occurrence variable O_i and the i -th leave variable L_i .
- The `open_minimum` constraint computes the minimum distance MIN from the leaves to the corresponding roots. The leave variable L_i is used in order to select only the distance variables corresponding to leaves.

- The `maximum` constraint computes the maximum distance MAX from the vertices to the roots. Since the maximum is achieved by a leaf we do not need to focus just on the leaves as it was the case for the minimum distance MIN.
- The linear constraint $\text{MAX} - \text{MIN} = R$ links together argument R to the minimum and maximum distances.

With respect to the **Example** slot we get the following conjunction of constraints:

```
tree(2, (index - 1 succ - 1, index - 2 succ - 5,
        index - 3 succ - 5, index - 4 succ - 7,
        index - 5 succ - 1, index - 6 succ - 1,
        index - 7 succ - 7, index - 8 succ - 5)),
domain((D1, D2, D3, D4, D5, D6, D7, D8), 0, 8),
DS1 ∈ [0, 8], element(1, (0, D2, D3, D4, D5, D6, D7, D8), DS1), D1 - 0 = 1,
DS2 ∈ [0, 8], element(5, (1, 0, D3, D4, D5, D6, D7, D8), DS2), D2 - D5 = 1,
DS3 ∈ [0, 8], element(5, (1, D2, 0, D4, D5, D6, D7, D8), DS3), D3 - D5 = 1,
DS4 ∈ [0, 8], element(7, (1, D2, D3, 0, D5, D6, D7, D8), DS4), D4 - D7 = 1,
DS5 ∈ [0, 8], element(1, (1, D2, D3, D4, 0, D6, D7, D8), DS5), D5 - 1 = 1,
DS6 ∈ [0, 8], element(1, (1, 3, 3, D4, 2, 0, D7, D8), DS6), D6 - 1 = 1,
DS7 ∈ [0, 8], element(7, (1, 3, 3, D4, 2, 2, 0, D8), DS7), D7 - 0 = 1,
DS8 ∈ [0, 8], element(5, (1, 3, 3, 2, 2, 2, 1, 0), DS8), D8 - 2 = 1,
global_cardinality((1, 5, 5, 7, 1, 1, 7, 5), (val - 1 noccurrence - 3,
                                             val - 2 noccurrence - 0,
                                             val - 3 noccurrence - 0,
                                             val - 4 noccurrence - 0,
                                             val - 5 noccurrence - 3,
                                             val - 6 noccurrence - 0,
                                             val - 7 noccurrence - 2,
                                             val - 8 noccurrence - 0)),
1 ⇔ 3 > 0, 0 ⇔ 0 > 0, 0 ⇔ 0 > 0, 0 ⇔ 0 > 0,
1 ⇔ 3 > 0, 0 ⇔ 0 > 0, 1 ⇔ 2 > 0, 0 ⇔ 0 > 0,
open_minimum(MIN, (var - 3 bool - 1, var - 0 bool - 0,
                  var - 0 bool - 0, var - 0 bool - 0,
                  var - 3 bool - 1, var - 0 bool - 0,
                  var - 2 bool - 1, var - 0 bool - 0)),
maximum(MAX, (1, 3, 3, 2, 2, 2, 1, 3)),
MAX - MIN = R = 1.
```

See also

related: `balance` (*balanced tree versus balanced assignment*).

root concept: `tree`.

used in reformulation: `domain`, `element`, `global_cardinality`, `maximum`, `open_minimum`, `tree`.

Keywords

constraint type: graph constraint, graph partitioning constraint.

final graph structure: connected component, `tree`.

modelling: balanced tree, functional dependency.

Arc input(s)	NODES
Arc generator	<code>CLIQUE</code> \mapsto <code>collection(nodes1, nodes2)</code>
Arc arity	2
Arc constraint(s)	<code>nodes1.succ = nodes2.index</code>
Graph property(ies)	<ul style="list-style-type: none"> • <code>MAX_NSCC</code> \leq 1 • <code>NCC</code> = NTREES • <code>RANGE_DRG</code> = R

Graph model

Parts (A) and (B) of Figure 5.767 respectively show the initial and final graph associated with the **Example** slot. Since we use the `RANGE_DRG` graph property, we respectively display the longest and shortest paths of the final graph with a bold and a dash line.

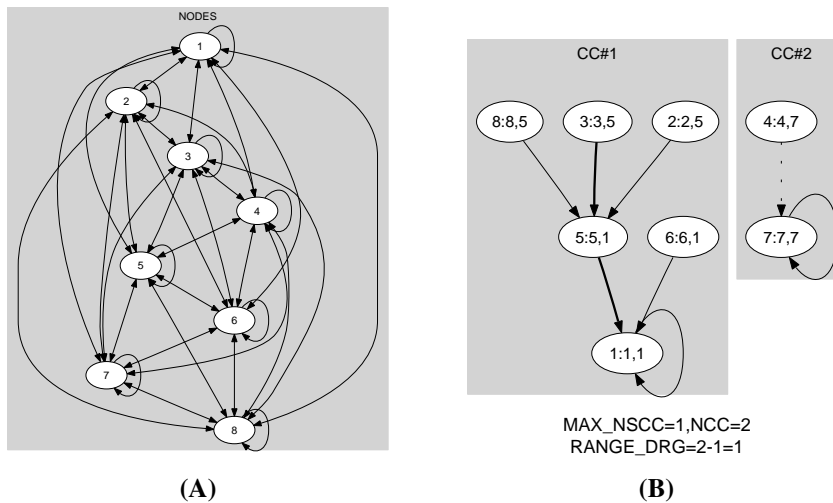


Figure 5.767: Initial and final graph of the `tree_range` constraint