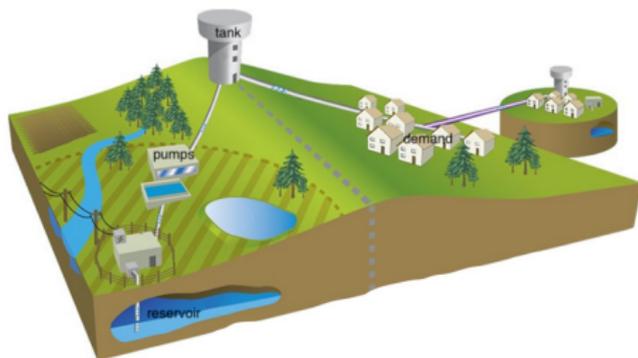
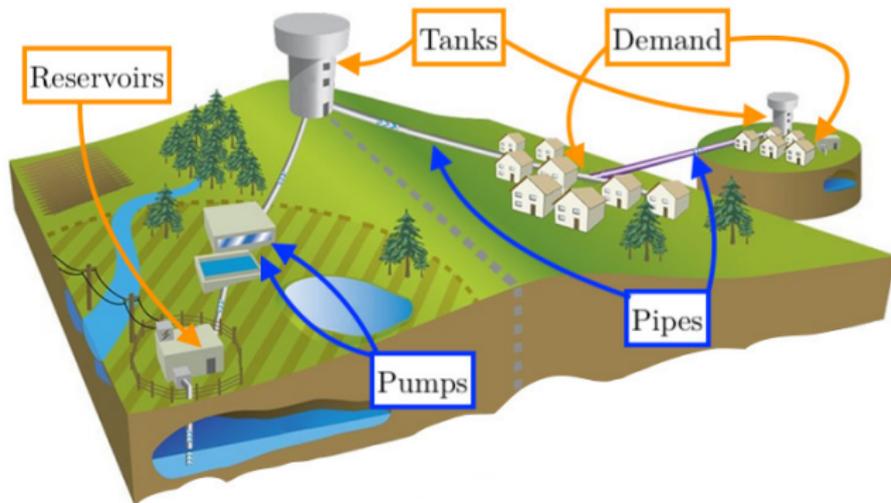


Extended LP formulation for pump scheduling in water distribution networks

Gratien Bonvin and Sophie Demassez (CMA, Mines ParisTech/PSL)



drinking water distribution network



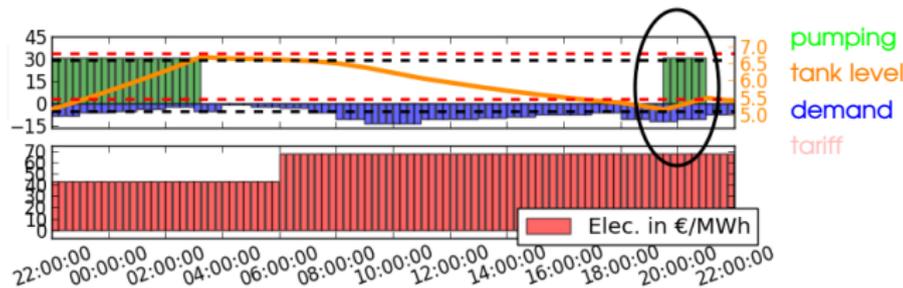
- ▶ **nodes**: reservoirs J_R , tanks J_T , junctions (demand nodes) J_J
- ▶ **arcs**: pipes L , pumps K , valves V

operating water distribution networks

- ▶ tanks = storage: dissociate water pumping/supplying times

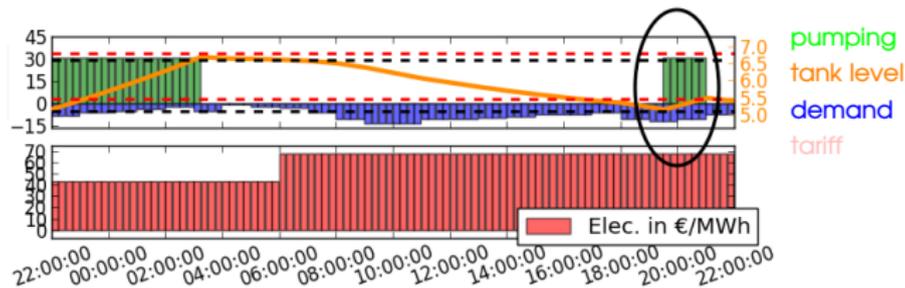
operating water distribution networks

- ▶ tanks = storage: dissociate water pumping/supplying times
- ▶ a scheduling problem: when to switch on/off pumps K and how to use the tanks J_T **limited** storage to satisfy the predicted demand D_{jt} at any junction $j \in J_J$ at any time $t = 1, \dots, T$ at the lowest cost ?



operating water distribution networks

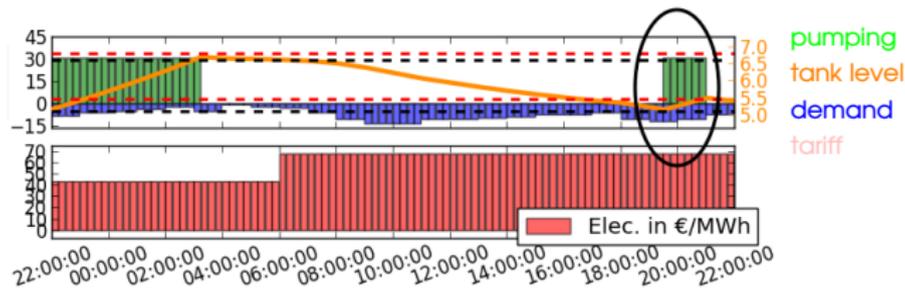
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- ▶ the historic day/night strategy is not compatible with dynamic tariffs

operating water distribution networks

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- ▶ the historic day/night strategy is not compatible with dynamic tariffs
- ▶ a highly **combinatorial** $O(2^{K.T})$, highly **non-convex** scheduling problem

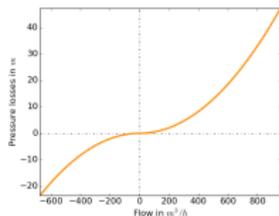
non-convex flow/head relation

- ▶ minimum hydraulic head (elevation + pressure) required to supply a node

non-convex flow/head relation

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pipe: head loss

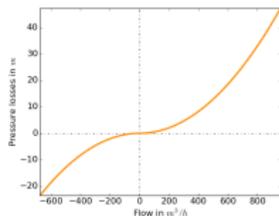


$$\Delta h = Aq|q| + Bq$$

non-convex flow/head relation

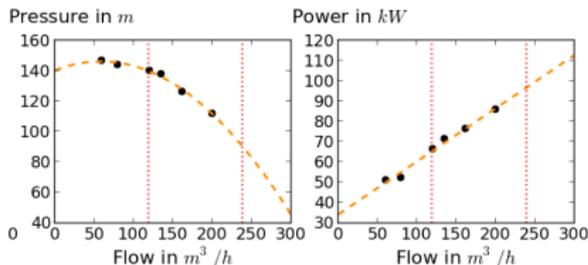
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$$\Delta h = Aq|q| + Bq$$

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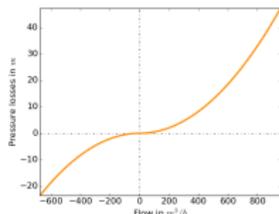


$$\Delta h = -Fq^2 + G, \quad p = Cq + E$$

non-convex flow/head relation

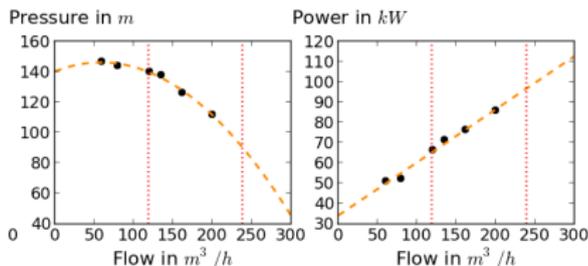
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pipe: head loss



$$\Delta h = Aq|q| + Bq$$

pump: head increase + power



$$\Delta h = -Fq^2 + G, \quad p = Cq + E$$

- ▶ **good news:** at time t and demand $D_t \in \mathbb{R}^{J_J}$, given a pump configuration $X \in \{0, 1\}^K$ and tank heads $H \in \mathbb{R}^{J_T}$, there is at most one possible flow/head $(q, h) \in \mathbb{R}^{L \times J}$ solution, which can quickly be computed with the Newton method (TODINI-PILATI88).

two main solution approaches

relax the NL part of MINLP

$$\min \sum_{t \in T} \sum_{k \in K} C_t \Delta_t (C_k q_{kt} + E_k x_{kt})$$

$$\text{s.t. } \sum_{j \in L} q_{jyt} - \sum_{j \in L} q_{jit} = D_{jt} \quad \forall t, j \in J_J$$

$$\sum_{j \in L} q_{jyt} - \sum_{j \in L} q_{jit} = \frac{S_j}{\Delta_t} (h_{yt} - h_{y(t-1)}) \quad \forall t, j \in J_T$$

$$(h_{yt} - h_{it} + F_{ijt} q_{ijt}^2 + G_{ij}) x_{ijt} = 0 \quad \forall t, ij \in K$$

$$h_{it} - h_{jt} = A_{ij} |q_{ijt}| q_{ijt} + B_{ij} q_{ijt} \quad \forall t, ij \in L_P$$

$$H_j^{\min} \leq h_{jt} \leq H_j^{\max} \quad \forall t, j \in J_T$$

$$q_{kt} \leq Q_k^{\max} x_{kt} \quad \forall t, k \in K$$

$$x_{kt} \in \{0, 1\} \quad \forall t, k \in K$$

PWL approximation (MORSI12, MENKE16, ...)

convex relaxation (BONVIN17, BONVIN19)

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$$\begin{aligned} \min \quad & \sum_{t \in T} \sum_{k \in K} C_t \Delta_t (C_k q_{kt} + E_k x_{kt}) \\ \text{s.t.} \quad & \sum_{\tilde{j} \in L} q_{\tilde{j}t} - \sum_{j \in L} q_{jt} = D_{jt} & \forall t, j \in J_J \\ & \sum_{\tilde{j} \in L} q_{\tilde{j}t} - \sum_{j \in L} q_{jt} = \frac{S_j}{\Delta_t} (h_{jt} - h_{j(t-1)}) & \forall t, j \in J_T \\ & (h_{jt} - h_{it} + F_{\tilde{j}t} q_{\tilde{j}t}^2 + G_{\tilde{j}t}) x_{\tilde{j}t} = 0 & \forall t, \tilde{j} \in K \\ & h_{it} - h_{jt} = A_{\tilde{j}t} |q_{\tilde{j}t}| q_{\tilde{j}t} + B_{\tilde{j}t} q_{\tilde{j}t} & \forall t, \tilde{j} \in L_P \\ & H_j^{\min} \leq h_{jt} \leq H_j^{\max} & \forall t, j \in J_T \\ & q_{kt} \leq Q_k^{\max} x_{kt} & \forall t, k \in K \\ & x_{kt} \in \{0, 1\} & \forall t, k \in K \end{aligned}$$

PWL approximation (MORSI12, MENKE16, ...)

convex relaxation (BONVIN17, BONVIN19)

separate feasibility/optimization

choose configurations



simulate hydraulics

metaheuristics, ex: GA (MACKLE95, ...),

Benders decomposition (NAOUM15),

lagrangian relaxation (GHADDAR15)

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convex relaxation (BONVIN17, BONVIN19)

▶ many binaries

separate feasibility/optimization

choose configurations



simulate hydraulics

metaheuristics, ex: GA (MACKLE95, ...),

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▶ slow convergence

model decomposition

the compact model

$$\min \sum_{t \in T} \sum_{k \in K} C_t \Delta_t (C_k q_{kt} + E_k x_{kt})$$

$$\text{s.t.} \quad \sum_{\tilde{j} \in L} q_{\tilde{j}t} - \sum_{j \in L} q_{jt} = D_{jt} \quad \forall t, j \in J_J$$

$$\sum_{\tilde{j} \in L} q_{\tilde{j}t} - \sum_{j \in L} q_{jt} = \frac{S_j}{\Delta_t} (h_{jt} - h_{j(t-1)}) \quad \forall t, j \in J_T$$

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- ▶ min pump power consumption
- ▶ flow conservation at junctions
- ▶ flow conservation at tanks
- ▶ head increase by pumps
- ▶ head losses in pipes
- ▶ tank capacities
- ▶ pump capacities
- ▶ pumps on/off

model decomposition

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rewrite one-time steps

$$\min \sum_{t \in T} \sum_{k \in K} C_t \Delta_t (C_k q_{kt} + E_k x_{kt})$$

$$\text{s.t. } h_{jt} - h_{j(t-1)} = \frac{\Delta_t}{S_j} \left(\sum_{\tilde{j} \in L} q_{\tilde{j}t} - \sum_{j \in L} q_{jt} \right) \quad \forall t, j \in J_T$$

$$(x_t, q_t, h_t) \in S_t \quad \forall t$$

- S_t set of feasible pump/flow/head configurations to supply demand D_t

model decomposition

compact model

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extended model

$$\begin{aligned} \min \quad & \sum_{t \in T} \sum_{s \in S_t} C_t P^s \Delta_t y_{st} \\ \text{s.t.} \quad & h_{jt} - h_{j(t-1)} = \sum_{s \in S_t} R_j^s \Delta_t y_{st} \quad \forall t, j \in J_T \\ & h_{jt} = \sum_{s \in S_t} H_j^s y_{st} \quad \forall t, j \in J_T \\ & \sum_{s \in S_t} y_{st} = 1 \quad \forall t \\ & y_{st} \in \{0, 1\} \quad \forall t, s \in S_t \end{aligned}$$

- ▶ $P \in \mathbb{R}$ power consumption, $R \in \mathbb{R}^{J_T}$ tank filling rate, $H \in \mathbb{R}^{J_T}$ tank head
- ▶ $|S_t| = \infty$ but from (TODINI&PILATI88):
- ▶ (at most) one $s \in S_t$ for each $x_t \in \{0, 1\}^K$ and $h_t \in [H_t^{\min}, H_t^{\max}] \subseteq \mathbb{R}^{J_T}$

proposed approximation

extended model

- ▶ relax the integrality constraints

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- ▶ relax the integrality constraints
- ▶ relax the head/configuration linking constraint

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$$\min \sum_{t \in T} \sum_{s \in \mathcal{S}'_t} C_t P^s \Delta_t y_{st}$$

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- ▶ relax the integrality constraints
- ▶ relax the head/configuration linking constraint
- ▶ restrict to columns $s \in \mathcal{S}'_t \subseteq \mathcal{S}_t$ with $H_j^s = \frac{H_j^{\max} - H_j^{\min}}{2}$, $\forall j \in J_T$

motivations

- ▶ integrality constraints are artificial: pumps can physically be operated during a time step

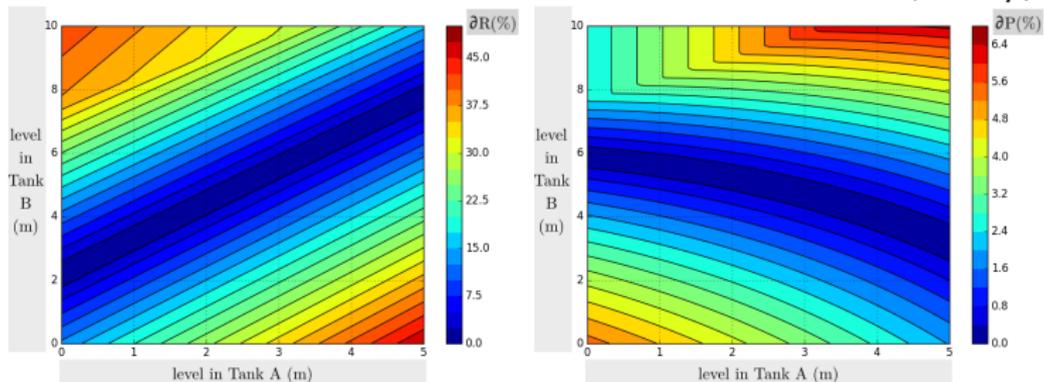
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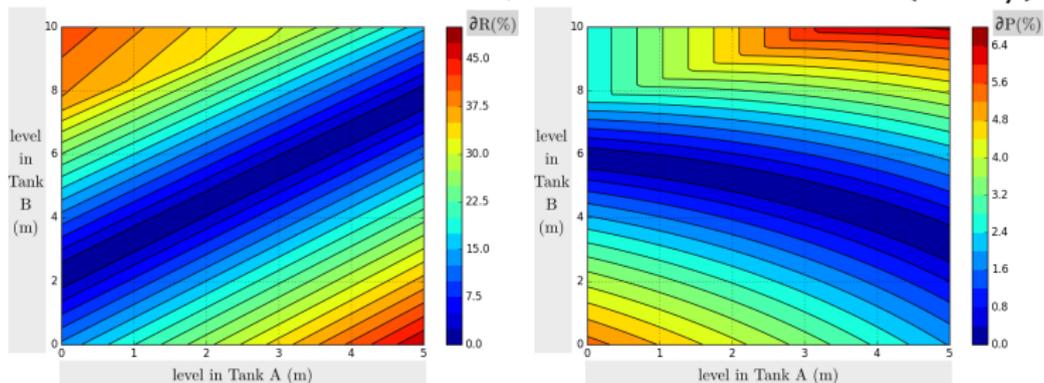
ex: relative errors on R and P for \neq levels in tanks A and B in (Van Zyl)



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- ▶ $|\mathcal{S}'_t| < 2^{|K|}$ AND can be computed **efficiently**

generating S'_t

- ▶ apply Newton method: fix $D_t \in \mathbb{R}^{J_J}$ and $H_t \in \mathbb{R}^{J_T}$, then compute Q^s then (P^s, R^s) (if feasible) for all $X^s \in \{0, 1\}^K$

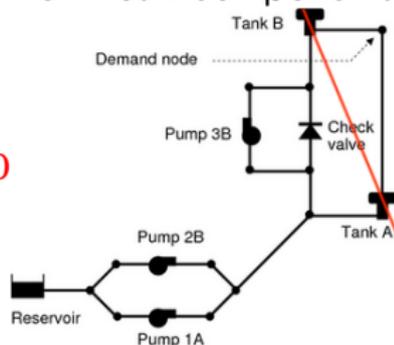
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- ▶ **network decomposition:** split at tank nodes and compute flows independently on each component

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- ▶ example: Van Zyl network has 2 components:

$$|K \cup V| = 4, |J_J| = 0$$



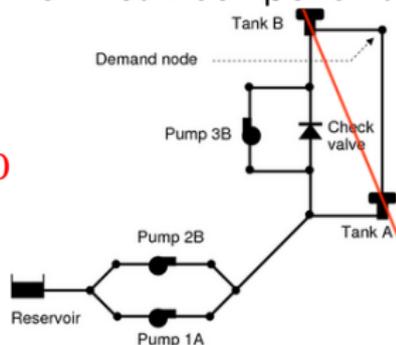
$$|K| = 0, |J_J| = 1$$

solve $2^4 + |T|$ flows to generate $2^4 \cdot |T|$ columns (max)

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- ▶ symmetry breaking: $D_{t_1} = D_{t_2} \Rightarrow S'_{t_1} = S'_{t_2}$

generalization

- ▶ variable speed pumps have continuous operation modes: either off or speed $w_k \in [W_k^{\min}, W_k^{\max}]$

generalization

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- ▶ approximation: sample $N_k + 1$ modes in the allowed speed range:

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generalization

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- ▶ choose the sampling step carefully

$N_k + 1$	2	3	4	5	6	7	8	9	10
$ S'_t $	21	52	105	186	301	456	657	910	1221
Z'	244.44	242.15	215.62	215.34	217.50	213.95	211.70	212.97	212.20

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- ▶ also for pressure-reducing valves: either open or pressure reduction $p_v \in [p_v^{\min}, p_v^{\max}]$

approximated solution

- ▶ solve the extended LP model and get for each time t the active configurations $C_t^* = \{s \in \mathcal{S}'_t \mid y_{st} > 0\}$ of durations $\delta_s^* = \Delta_t y_{st}$. Order each set C_t^* arbitrarily and get an approximated pumping plan:

$$P^* = \underbrace{s_0, s_1, \dots, s_{n_0}}_{C_0^*}, \underbrace{s_{n_0+1}, \dots, s_{n_0+n_1}}_{C_1^*}, \underbrace{\dots}_{C_{T-1}^*}$$

- ▶ start with $i = 0$, apply the Newton method to s_i with $H_i \in \mathbb{R}^{J_T}$ to get the actual flow rates Q_i , then compute the filling rates R_i and update tank heads $H_{i+1} = H_i + \delta_i R_i$.
- ▶ plan P^* is *valid* if $H^{\min} \leq H_i \leq H^{\max}$ for all i

to a close feasible solution

- ▶ each pump can be switched at any time... not in any old way
- ▶ operational constraints to prevent premature aging, e.g
 N max nb of switches on, τ_0/τ_1 max nb of consecutive times off/on

$$\sum_{t \in \mathcal{T}} y_{kt} \leq N,$$

$$y_{kt} \geq x_{kt} - x_{k(t-1)}, \quad \forall t$$

$$x_{kt'} \geq y_{kt}, \quad \forall t, t' \in [t, t + \tau_1]$$

$$z_{kt} \geq x_{k(t-1)} - x_{kt}, \quad \forall t$$

$$x_{kt'} \leq 1 - z_{kt}, \quad \forall t, t' \in [t, t + \tau_0]$$

- ▶ find a **feasible** plan P (with one configuration per time step, satisfying tank capacities and operational constraints) at a close distance of P^*
i.e. with $\delta_{kt} \approx \delta_{kt}^*$, the activity duration of pump k in time step t

combinatorial Benders local search

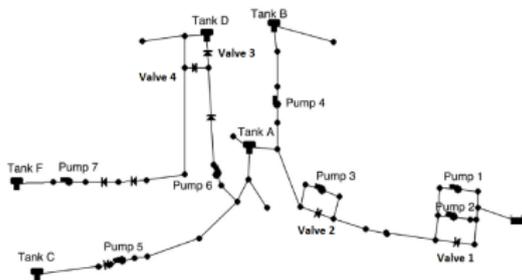
- ▶ solve (M) : $\min \sum_k \sum_t (\delta_{kt}^* - x_{kt} \Delta_t)^2 + \sum_{k \in K} (\sum_t \delta_{kt}^* - \sum_t x_{kt} \Delta_t)^2$
s.t.: (operational constraints), $x \in \{0, 1\}^{K \times T}$
- ▶ apply Newton method iteratively on each configuration x_t ,
 $t = 0, \dots, T - 1$, and get the actual flows-heads (Q, H)
- ▶ if some constraint is violated at time \bar{t} , add to (M) a no-good constraint

$$\sum_{t=1}^{\bar{t}} \left(\sum_{\substack{k \in K \\ X_{kt}=0}} x_{kt} + \sum_{\substack{k \in K \\ X_{kt}=1}} (1 - x_{kt}) \right) \geq 1$$

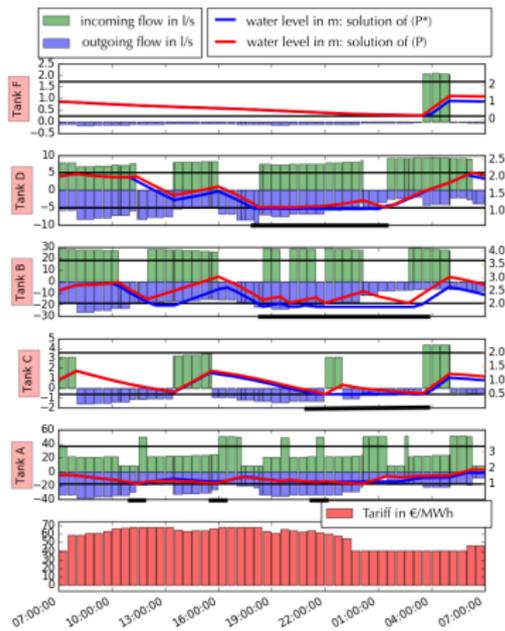
- ▶ try to correct the small violations by adjusting the time step durations Δ_t using the matheuristic from (BONVIN-DEMASSEY-LODI19)

computational results

near-feasible approximated solutions P^*

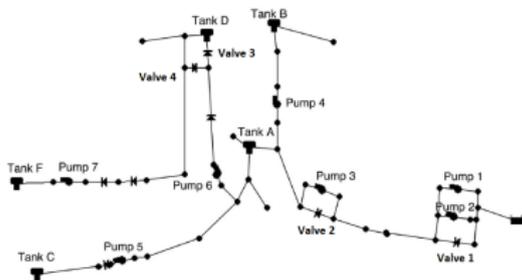


► Poormond instance (GHADDAR15)

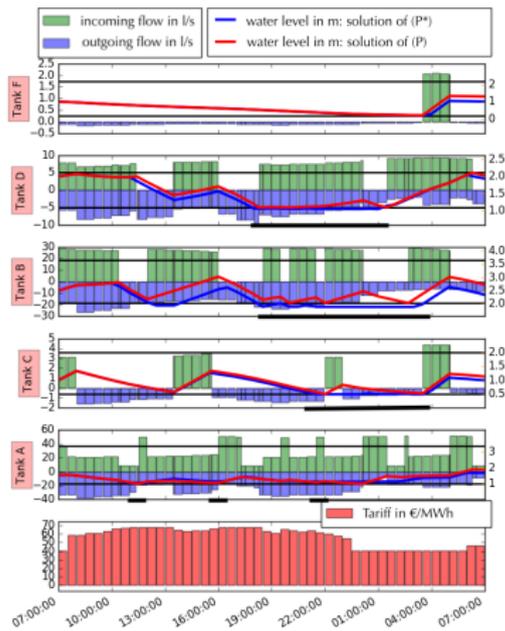


computational results

near-feasible approximated solutions P^*

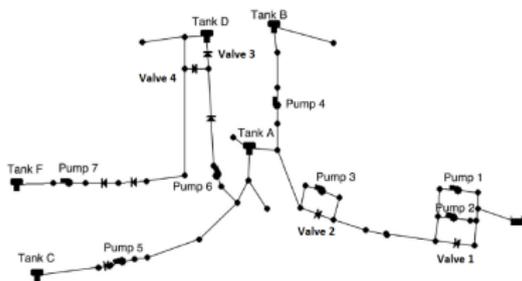


- ▶ Poormond instance (GHADDAR15)
- ▶ average relative error on $Q < 1\%$

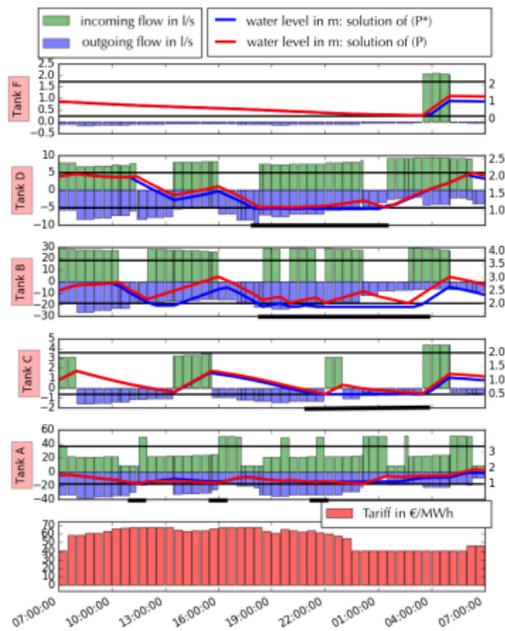


computational results

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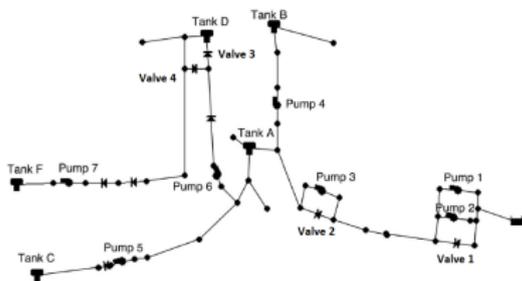


- ▶ Poormond instance (GHADDAR15)
- ▶ average relative error on $Q < 1\%$
- ▶ 3% (104) active columns for $|T| = 48$

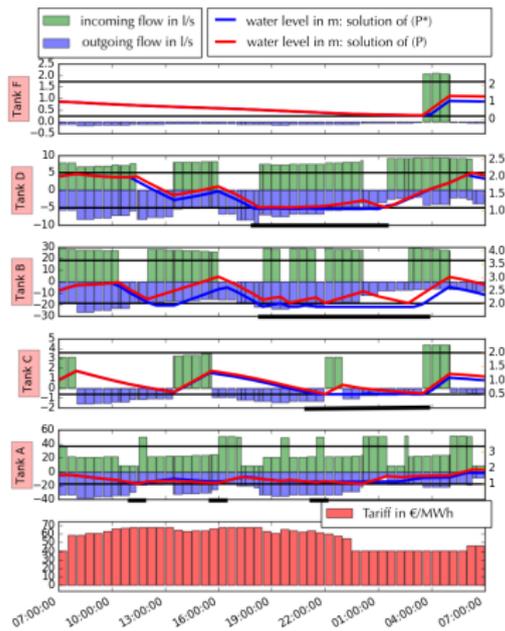


computational results

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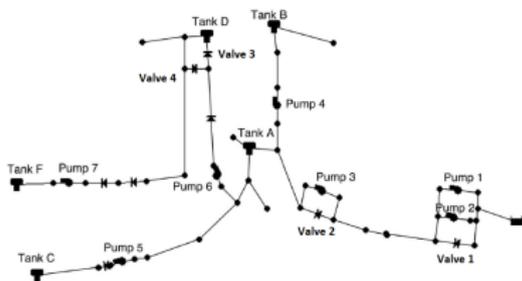


- ▶ Poormond instance (GHADDAR15)
- ▶ average relative error on $Q < 1\%$
- ▶ 3% (104) active columns for $|T| = 48$
- ▶ aging constraints are mostly satisfied

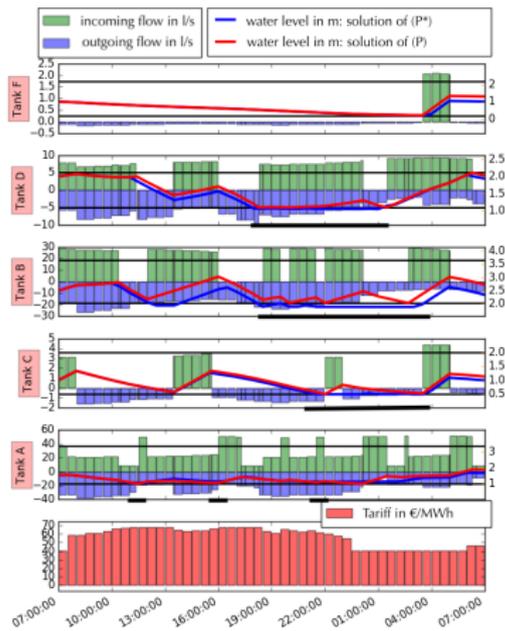


computational results

near-feasible approximated solutions P^*

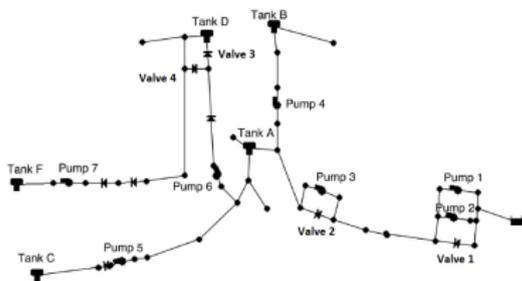


- ▶ Poormond instance (GHADDAR15)
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- ▶ feasible P in 1 iteration (LS + heuristic)

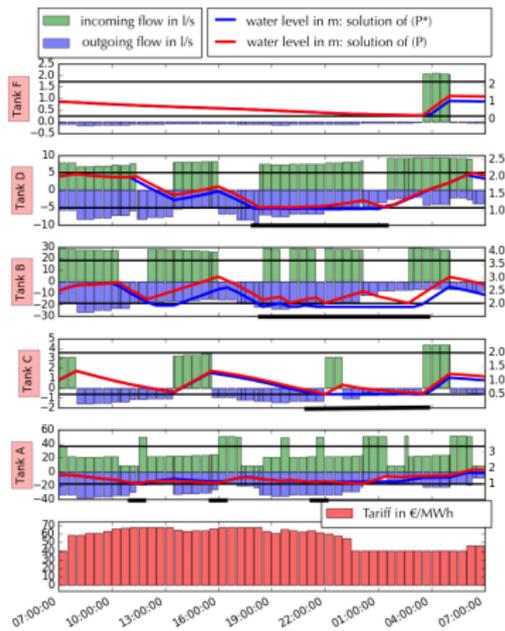


computational results

near-feasible approximated solutions P^*



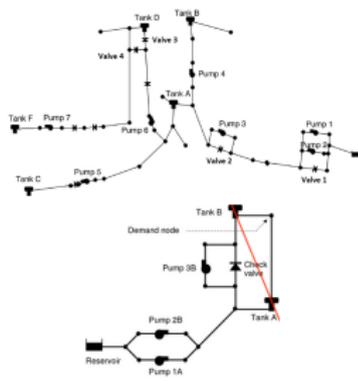
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- ▶ $Z = 111.03, Z^* = 117.5$ euros



computational results

fast heuristic

Day	Computation time (s)				Cost (euros)			
	S'	LP	LS	Total	LS	best	LS/LB	best/LB
Poormond								
P21	1.6	<0.1	16.3	17.9	117.50	112.48	8.2%	4.1%
P22	1.6	<0.1	11.2	12.8	118.55	116.49	5.6%	3.9%
P23	1.6	<0.1	8.0	9.6	120.93	120.85	4.1%	4.0%
P24	1.6	<0.1	10.9	12.5	137.05	134.99	4.6%	3.1%
P25	1.6	<0.1	21.2	22.8	98.74	92.53	9.8%	3.8%
Van Zyl								
Z21	2.1	<0.1	0.7	2.8	220.60	222.66	14.9%	15.7%
Z22	2.1	<0.1	1.7	3.8	230.07	230.69	14.1%	14.3%
Z23	2.1	<0.1	1.4	3.5	240.67	240.93	13.7%	13.8%
Z24	2.1	<0.1	0.6	2.6	267.77	268.91	14.4%	14.7%
Z25	2.1	<0.1	0.7	2.8	188.52	190.29	14.5%	15.3%



- ▶ best and LB computed in 1h with LP/NLP branch and check (BONVIN19)
- ▶ Van Zyl (sampling 6 speeds/3 pumps, 1 valve, $|T| = 48$)
 - ▶ $6^3 \times 2 \times 48 \approx 20,000$ configurations to evaluate
 - ▶ network decomposition: $6^3 \times 2 + 48 = 480$ to compute
 - ▶ P^* : 50 active configurations
 - ▶ get P by solving the compact NLP with fixed X

limits and perspectives

- ▶ evaluate the method on bigger networks: where are the instances ?

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- ▶ still an exponential number of configurations to compute: could we build \mathcal{S}'_t from historical data ?
- ▶ no optimality certificate: how to integrate the approximated model into a global optimization approach ?