

SCHEDULING PUMPS AND RESERVOIRS WITH INTEGER NONLINEAR PROGRAMMING AND DEEP LEARNING

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SimHydro 2025

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decision aid: compute one of the best possible options

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- *models are based on data forecasts*

machine learning

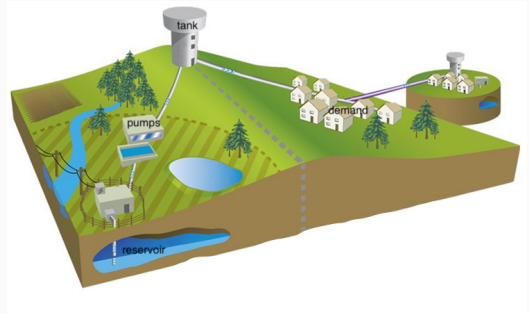
- predict from data
- no certificate
- data/computation intensive
- *algorithms are based on optimization*

combine MO and ML when models are complex but certificates required

LOAD SHIFTING IN DRINKING WATER DISTRIBUTION

pump in advance of demand to save energy

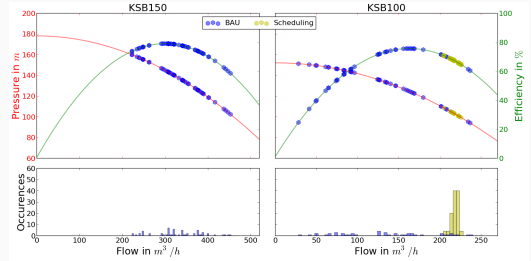
- water/energy storage tanks
- nonlinear efficiency
- dynamic electricity tariff



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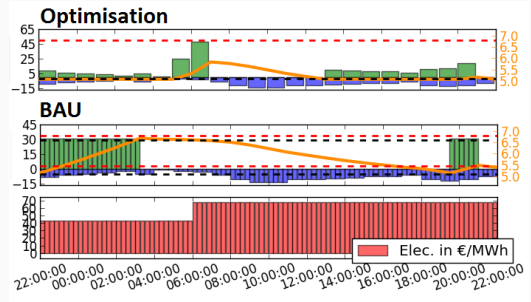
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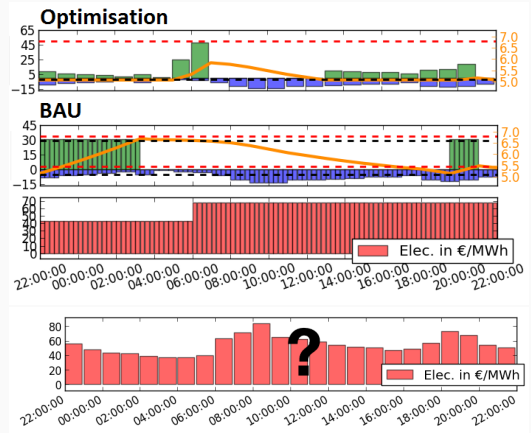
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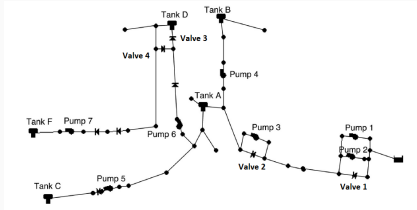
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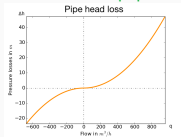


ACCURATE BUT COMPLEX ANALYTICAL MODEL

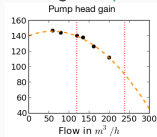


nonconvex flow/head loss equation $\Delta h = \phi(q)$

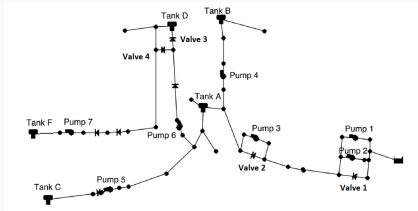
friction in pipes



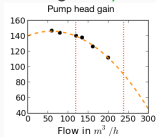
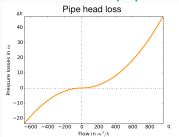
discharge in pumps



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mixed integer nonconvex model

$$\min \sum_t C_t \gamma_t(q_t, x_t) :$$

$$\underline{H}^R \leq h_t^R \leq \overline{H}^R \quad \forall t$$

$$h_{t+1}^R = h_t^R + \sigma q_t^R \quad \forall t$$

$$q_t^S = D_t^S \quad \forall t$$

$$(\Delta h_t - \phi(q_t))^T x_t = 0 \quad \forall t$$

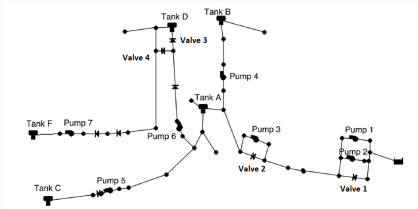
$$q_t^T (1 - x_t) = 0 \quad \forall t$$

on/off switch $x_{ta} \in \{0, 1\}$

arc flow q_{ta} and head loss Δh_{ta}

reservoir/service node inflow q_{tr}^R, q_{ts}^S and head h_t

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(q_t, h_t) is the **unique head/flow equilibrium** on open arcs x_t with node inflow D_t^S or head h_t^R

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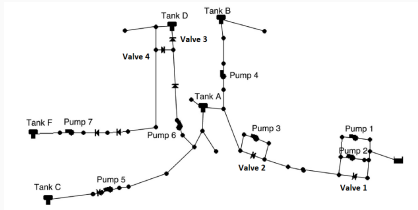
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- computing $(q_t, h_t) \in Eq(x_t, D_t^S, h_t^R)$ is easy (Todini & Pilati's Newton algorithm/EPANET)
- but optimizing $(x_t)_t$ is hard

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integer/nonconvex bilevel model

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1. approximation or relaxation

simplify some of the hardest parts

- PWL approx [Morsi12,...]
- linear relax [Burgschweiger09]
- lagrangian relax [Ghaddar15]
- convex relax + simulation [Bonvin21]

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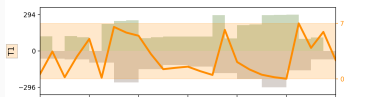
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tight tank limits, long time steps



⇒ scarce/sparse feasibility set in discrete x -space

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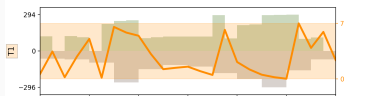
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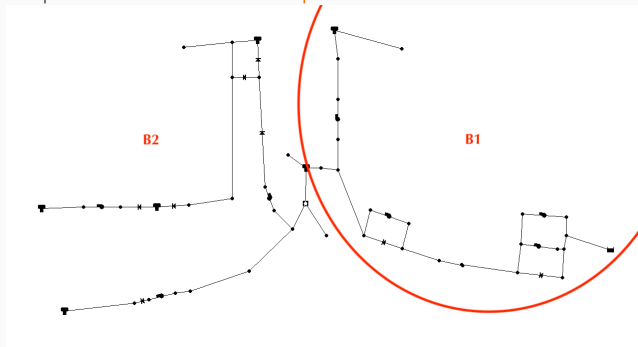
Sketch of the algorithm

1. fix the tank level profiles h^R
2. compute all equilibria $(q_t, h_t) \in Eq(x_t, D_t^S, h_t^R)$ for all config $x_t \forall t$
3. select the config/equilibrium of minimal cost $C_t \gamma_t(q_t, x_t) \forall t$
4. stop if $h_{t+1}^R \approx h_t^R + q_t^R$ or update h^R

SEARCH THE CONTINUOUS h^R -SPACE: IN PRACTICE

Step 2: compute all equilibria $(q_t, h_t) \in Eq(x_t, D_t^S, h_t^R)$ for all config $x_t \forall t$

splitting the equilibrium problems in time and in space enables us to enumerate the sub-configurations



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Step 4: update tank level profiles h^R closer to satisfy both $h_{t+1}^R \approx h_t^R + q_t^R$ and $\underline{H}^R \leq h_t^R \leq \overline{H}^R \forall t$

we adapted a variable splitting scheme alike ADMM: no convergence proof in this nonconvex case

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Step 0: compute initial tank level profiles h^R

we built a deep learning model to predict the optimal profiles from history

- using a (time) scaling mechanism to save on the training phase
- using Monte-Carlo dropouts to restart/diversify the search

CONCLUSION

- **integration** of machine learning, simulation and optimization
- time and space **decomposition**
- **reasoning on the implied storage state variables** instead of the discrete decision control variables
- practical scalability ? theoretical convergence ?
- other applications in water management ?

REFERENCES

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- papers available at <https://sofdem.github.io/>
- code available at <https://github.com/sofdem/gopslpnlpbb>